

TOPOLOGY OPTIMIZATION OF BINARY STRUCTURES UNDER DESIGN-DEPENDENT FLUID-STRUCTURE INTERACTION LOADS

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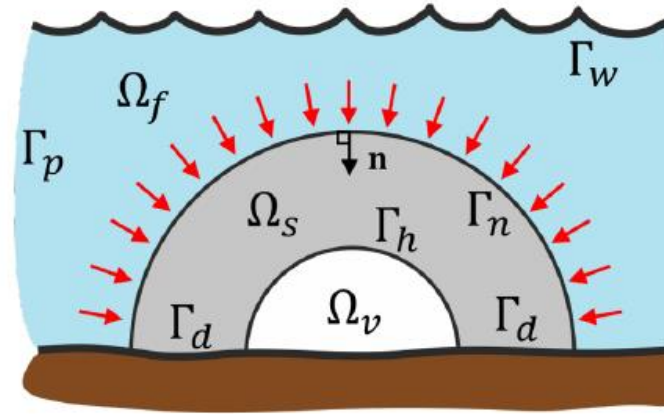


Contents

- Introduction – Fluid-structure interaction (FSI) in topology optimization (TO)
- Topology optimization of binary structures (TOBS)
- A new recipe for FSI design
- Results
- Conclusions

Introduction

- Multiphysics
 - Hydrostatic fluid pressure
 - Thermoelastic design
 - Acoustic-structure interaction
 - Fluid flow optimization
 - Acoustics
 - ...



[1] Picelli et al. (2019)

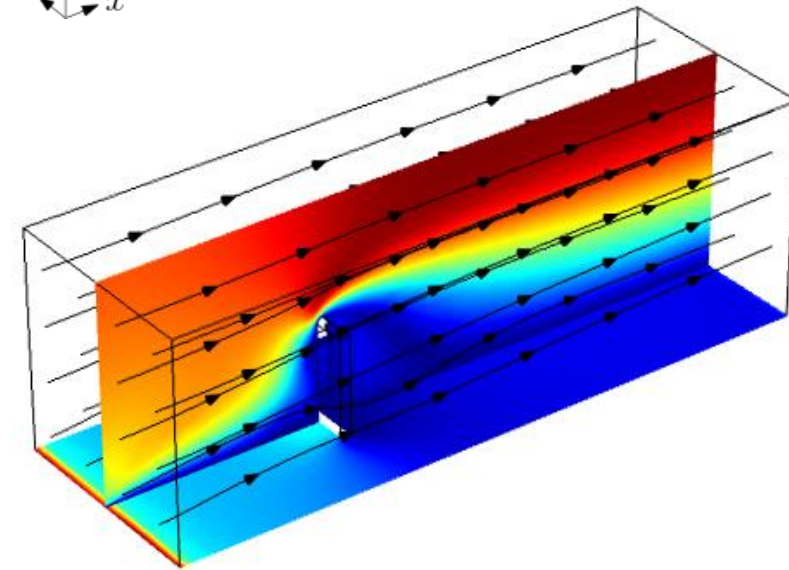
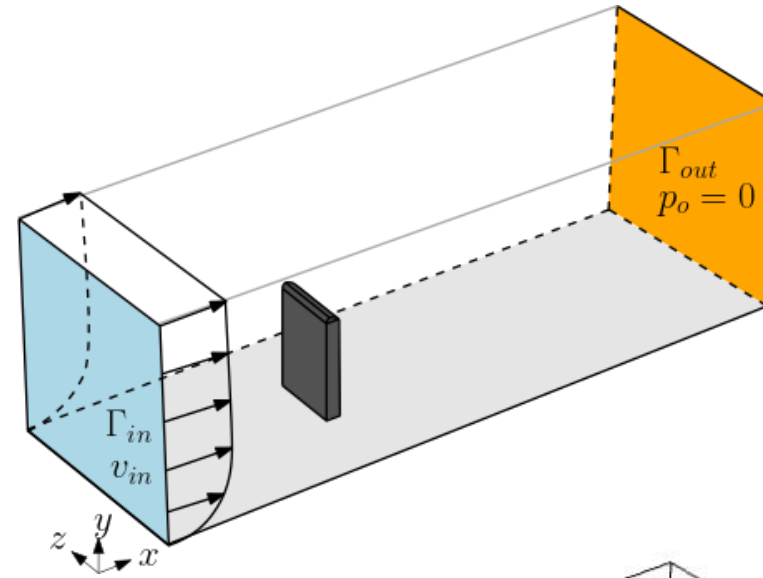
Underexplored and challenging!



www.marinetechologynews.com/news/sales-forum-subsea-announced-557928

Introduction

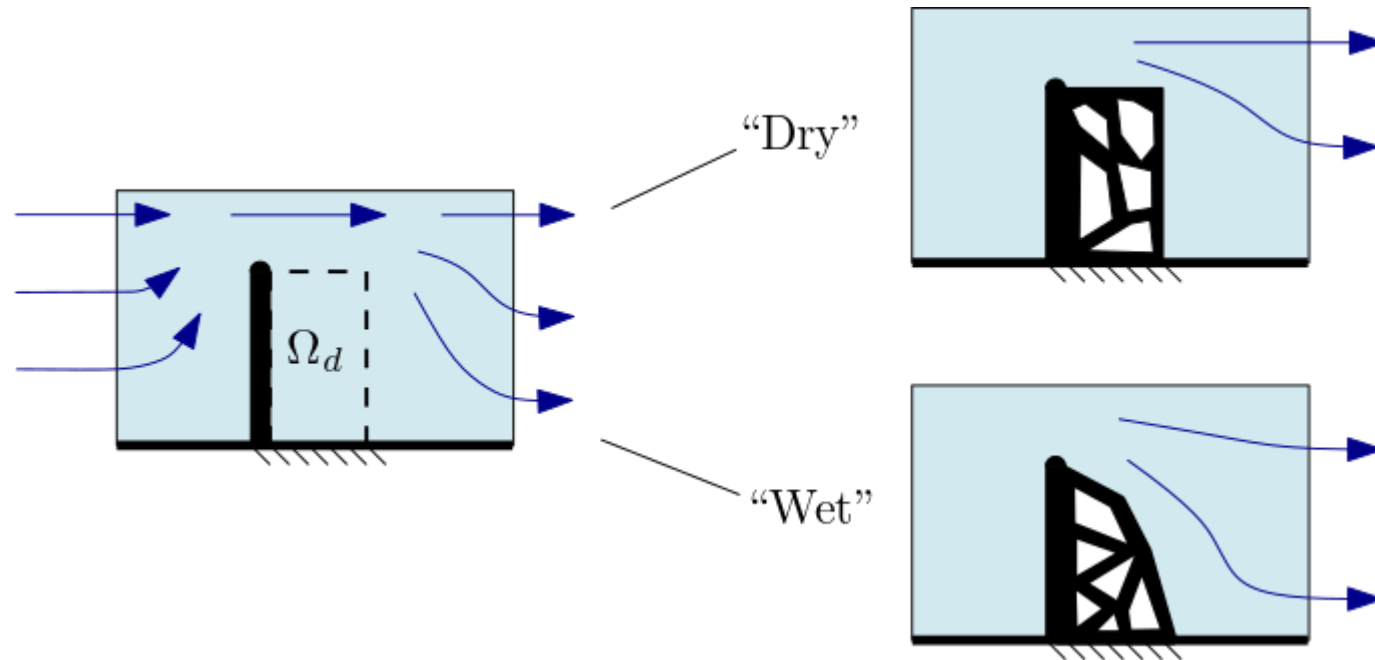
- Multiphysics
 - Hydrostatic fluid pressure
 - Thermoelastic design
 - Acoustic-structure interaction
 - Fluid flow optimization
 - Acoustics
 - ...
- Fluid-structure interaction (FSI)



Objectives

- Topology optimization of FSI problems
- Use the TOBS approach
- Create an algorithm to decouple analysis and optimization grid
- **Motivation:** create a methodology for FSI and other physics design

Topology Optimization in FSI problems

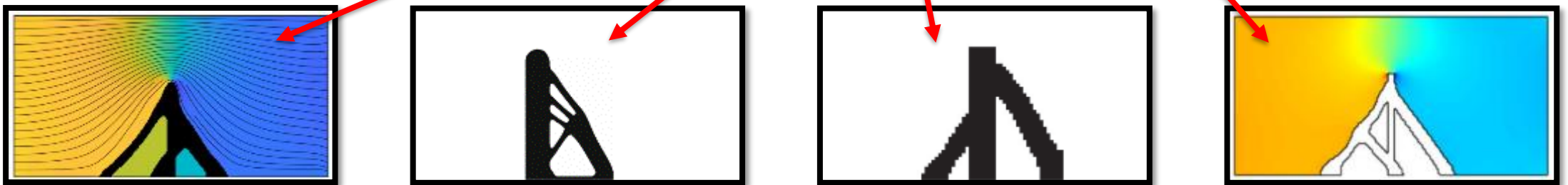


Design-dependent loading problem

[4] Jenkins and Maute (2016)

Topology Optimization in FSI problems

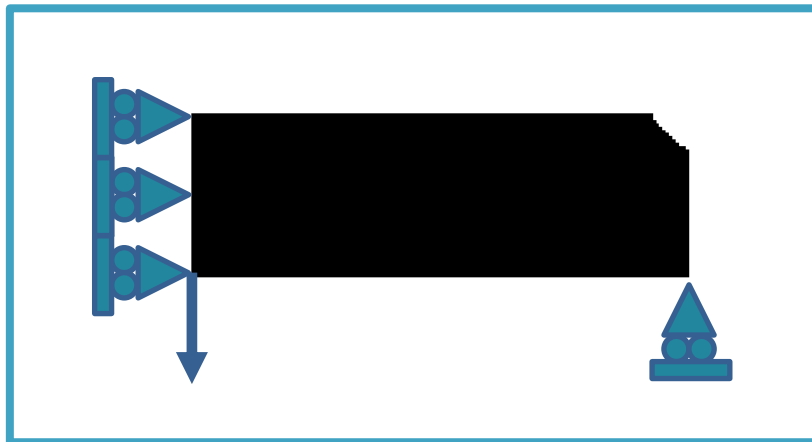
- Scientific and technological challenges
 - FSI design-dependent loading – equilibrium conditions
 - Strongly coupled phenomenon: fluid flow \leftrightarrow structural deformation
- Available TO methods: SIMP [2,3], LSM [4], BESO [5] and TOBS [6]



❖ [2] Lungaard et al. (2018); [3] Yoon (2010); [4] Jenkins and Maute (2016); [5] Picelli et al. (2017); [6] Picelli et al. (2020)

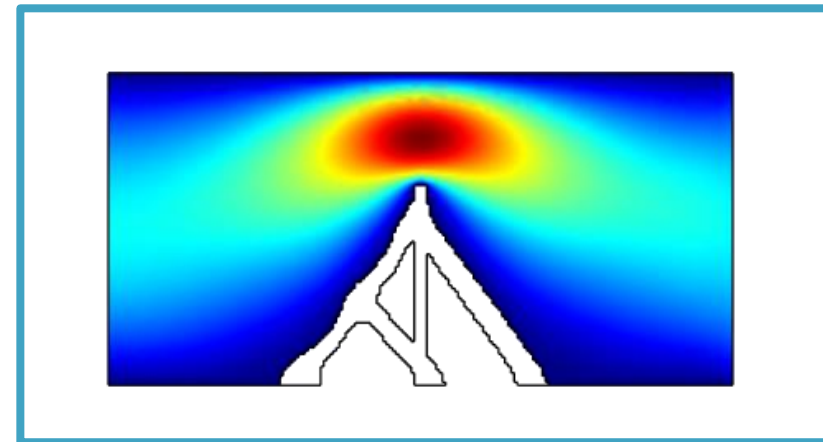
Topology Optimization in FSI problems

TOBS approach



[6] Sivapuram and Picelli (2018), [7] Picelli et al. (2020)

FSI simulation

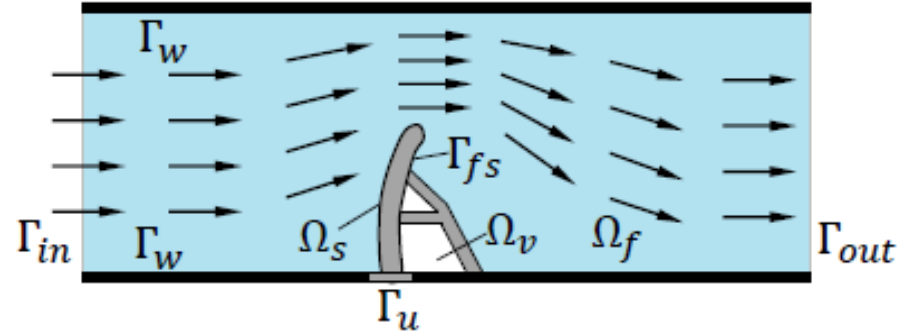


[8] Picelli, R., Ranjbarzadeh, S., Sivapuram, R., Gioria, RS, Silva, ECN, “Topology optimization of binary structures under design-dependent fluid-structure interaction loads” SMO 62:2101–2116 (2020)

- Binary $\{0,1\}$ design variables
 - Clear distinction between solid and fluid/void materials
 - Lesser or no effects at all from the material interpolation
 - Multiphysics simulation with separate domains

Topology Optimization in FSI problems

$$\begin{aligned} & \underset{\mathbf{x}}{\text{Minimize}} \quad C(\mathbf{x}) \\ & \text{Subject to} \quad V_i(\mathbf{x}) \leq \bar{V}_i, \quad i \in [1, N_g] \\ & \quad \quad \quad x_j \in \{0, 1\}, \quad j \in [1, N_d] \end{aligned}$$



Fluid domain (incompressible Navier-Stokes eqs.)

$$\begin{cases} \rho_f (\mathbf{v}_f \cdot \nabla \mathbf{v}_f) = -\nabla P_f + \mu \nabla^2 \mathbf{v}_f \\ \nabla \cdot (\mathbf{v}_f) = \mathbf{0} \end{cases}$$

Solid domain (linear elasticity)

Topology Optimization of Binary Structures (TOBS)

- The TOBS method

- Sequential approximate problems
- Binary design variables
- Sensitivity filtering
- Integer linear programming (ILP)
 - Branch-and-bound algorithm in CPLEX by IBM

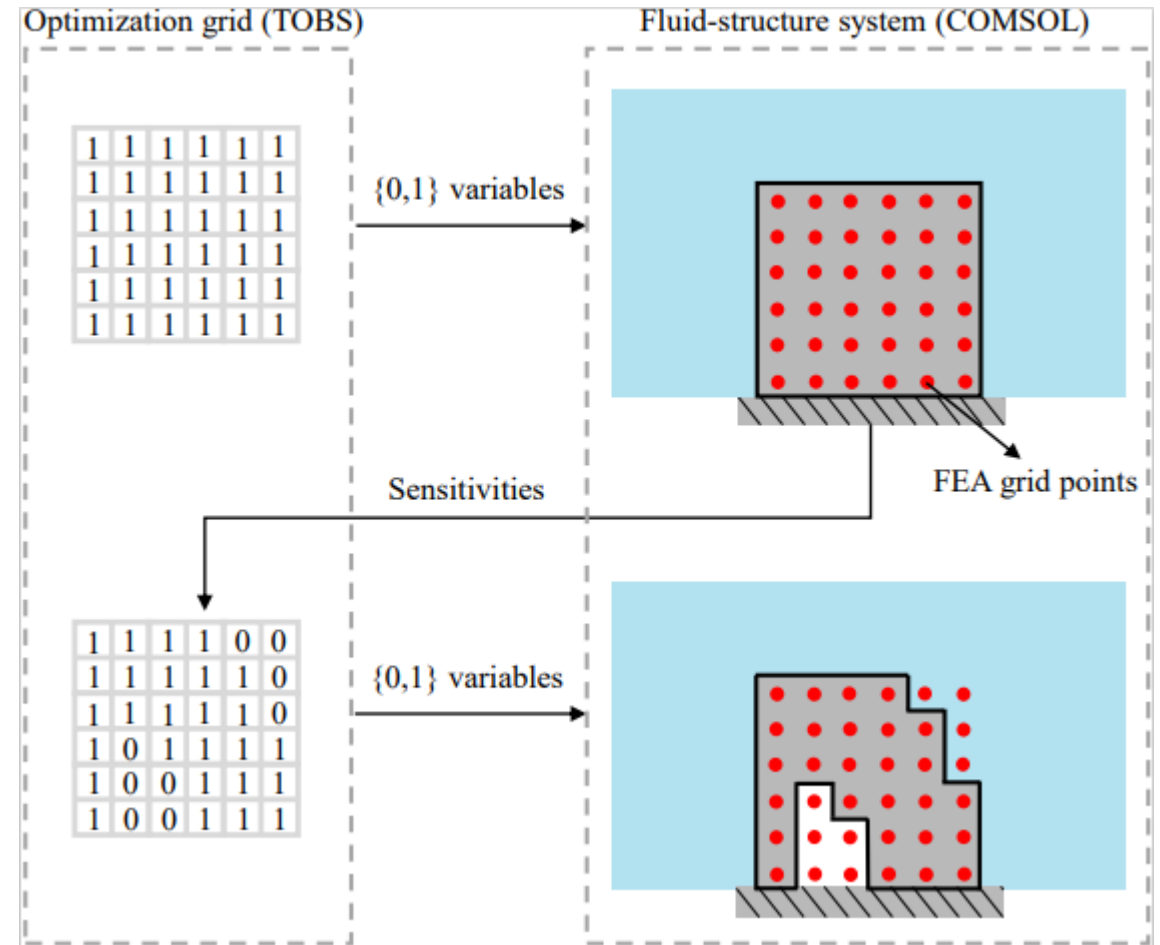
Educational paper:
[7] Picelli et al. (2020)

$$\begin{aligned}
 & \underset{\Delta \mathbf{x}^k}{\text{Minimize}} && \frac{\partial f(\mathbf{x}^k)}{\partial \mathbf{x}} \cdot \Delta \mathbf{x}^k, \\
 & \text{Subject to} && \frac{\partial g_i(\mathbf{x}^k)}{\partial \mathbf{x}} \cdot \Delta \mathbf{x}^k \leq \bar{g}_i - g_i(\mathbf{x}^k) := \Delta g_i^k, \quad i \in [1, N_g], \\
 & && \|\Delta \mathbf{x}^k\|_1 \leq \beta N_d, \\
 & && \Delta x_j^k \in \{-x_j^k, 1 - x_j^k\}, \quad j \in [1, N_d].
 \end{aligned}$$

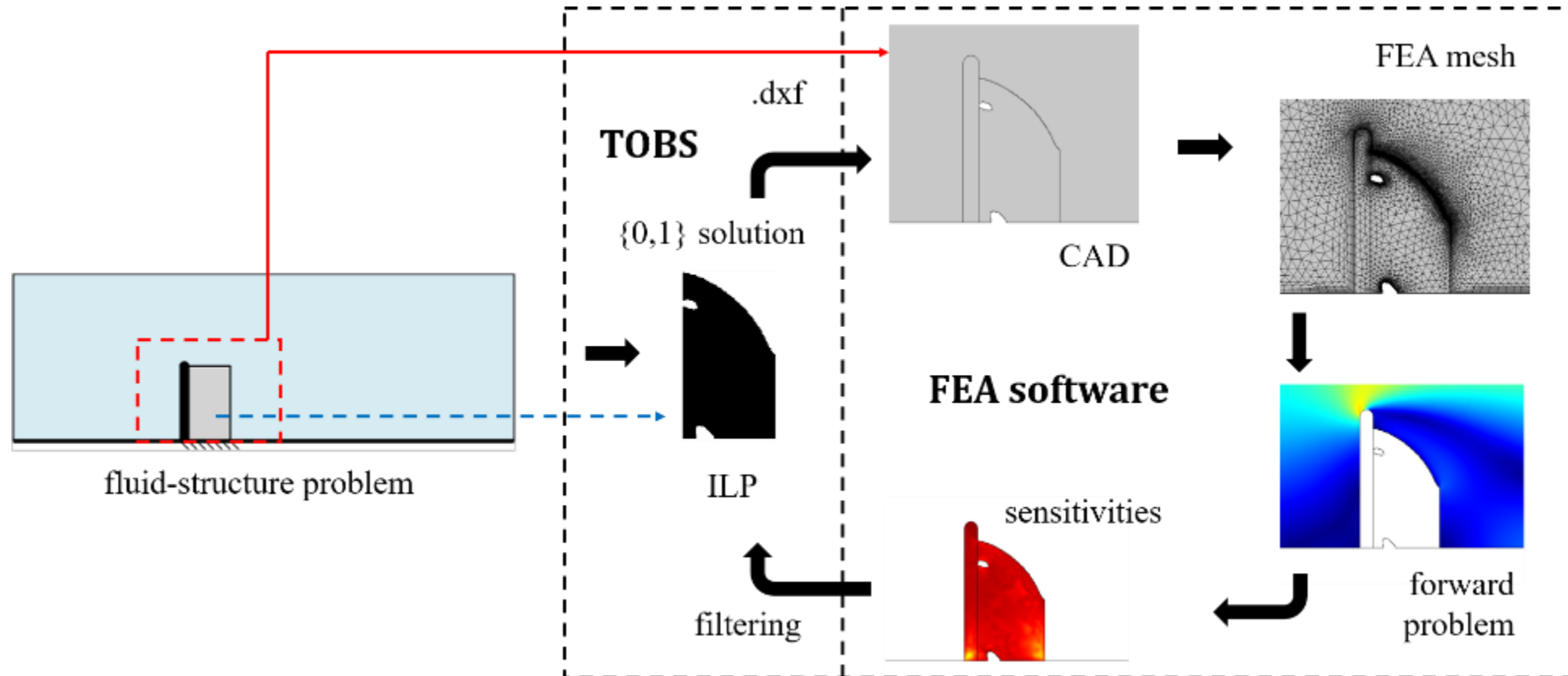
$$\Delta g_i^k = \begin{cases} -\epsilon_i g_i(\mathbf{x}^k) & : \bar{g}_i < (1 - \epsilon_i) g_i(\mathbf{x}^k), \\ \bar{g}_i - g_i(\mathbf{x}^k) & : \bar{g}_i \in [(1 - \epsilon_i) g_i(\mathbf{x}^k), (1 + \epsilon_i) g_i(\mathbf{x}^k)], \\ \epsilon_i g_i(\mathbf{x}^k) & : \bar{g}_i > (1 + \epsilon_i) g_i(\mathbf{x}^k), \end{cases}$$

FSI design with geometry trimming

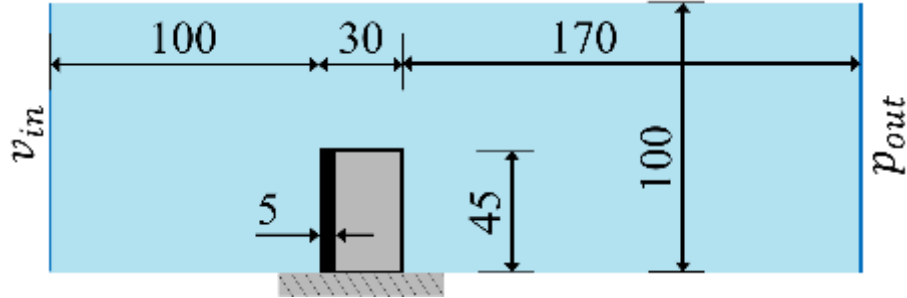
- Decoupling of optimization grid and FEA
 - Optimization module (TOBS)
 - FEA (COMSOL)
- Automatic differentiation
 - SIMP interpolation to aid derivation
- Geometry trimming



FSI design with geometry trimming



Examples: the wall



Minimum compliance
 $\bar{V} = 35\%$

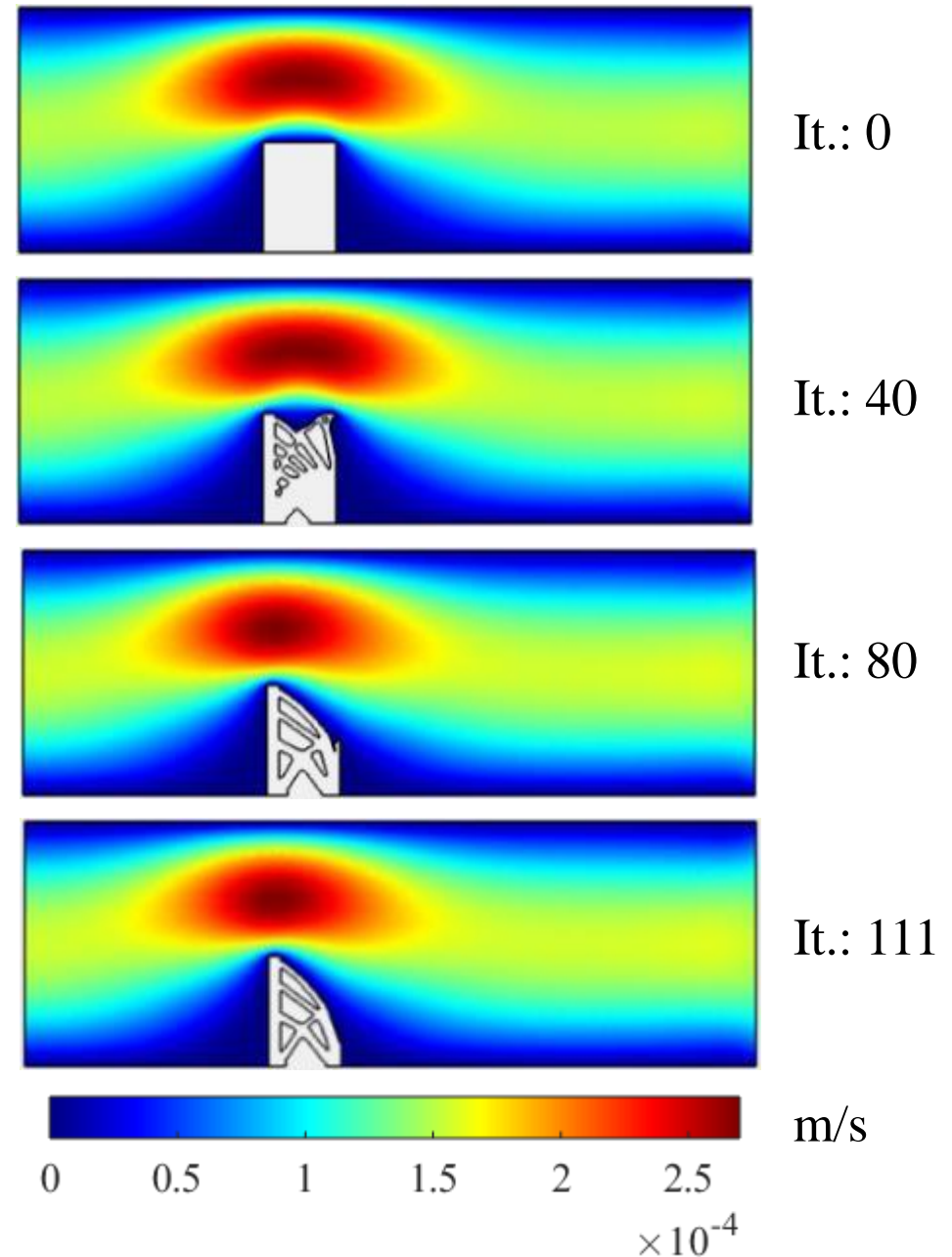
Solid: $E = 2 \cdot 10^5$ Pa, $\nu = 0.3$

Fluid: water

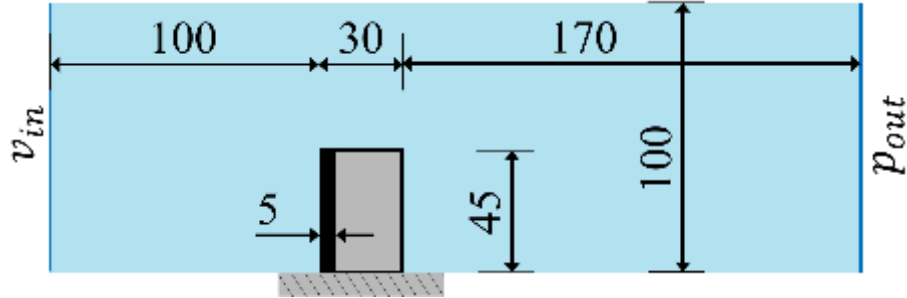
Re = 0.01

$\epsilon = 0.01$

$\beta = 0.05$



Examples: the wall



Minimum compliance
 $\bar{V} = 35\%$

Solid: $E = 2 \cdot 10^5$ Pa, $\nu = 0.3$

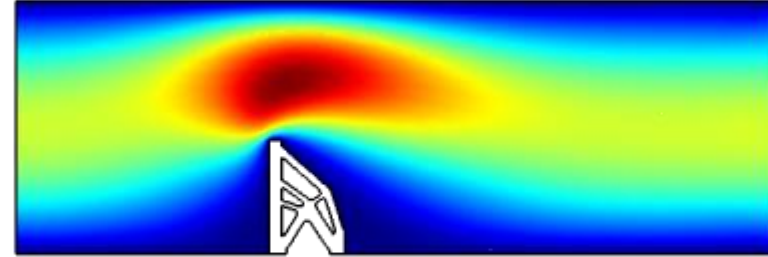
Fluid: water

$Re = 0.01$

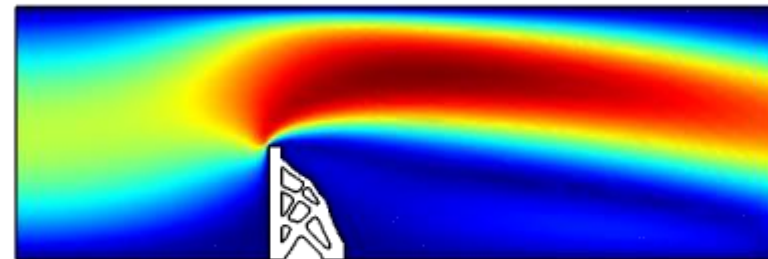
$\epsilon = 0.01$

$\beta = 0.05$

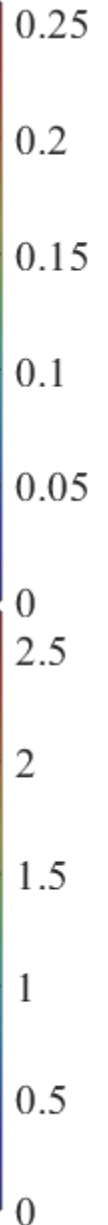
$Re = 10$



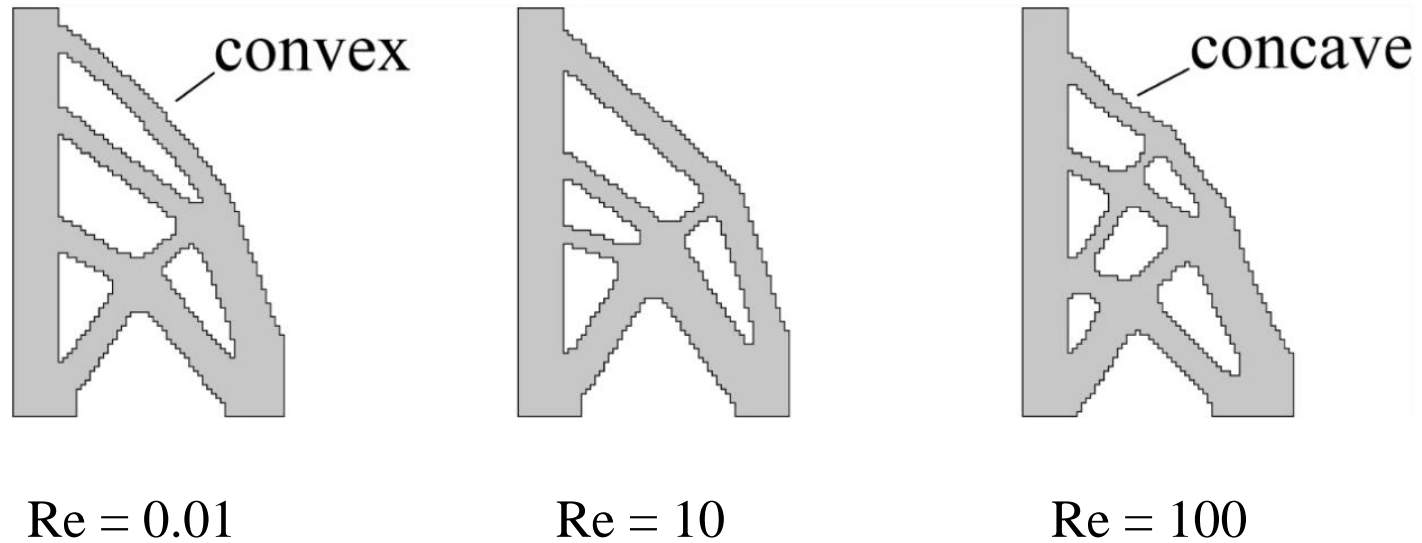
$Re = 100$



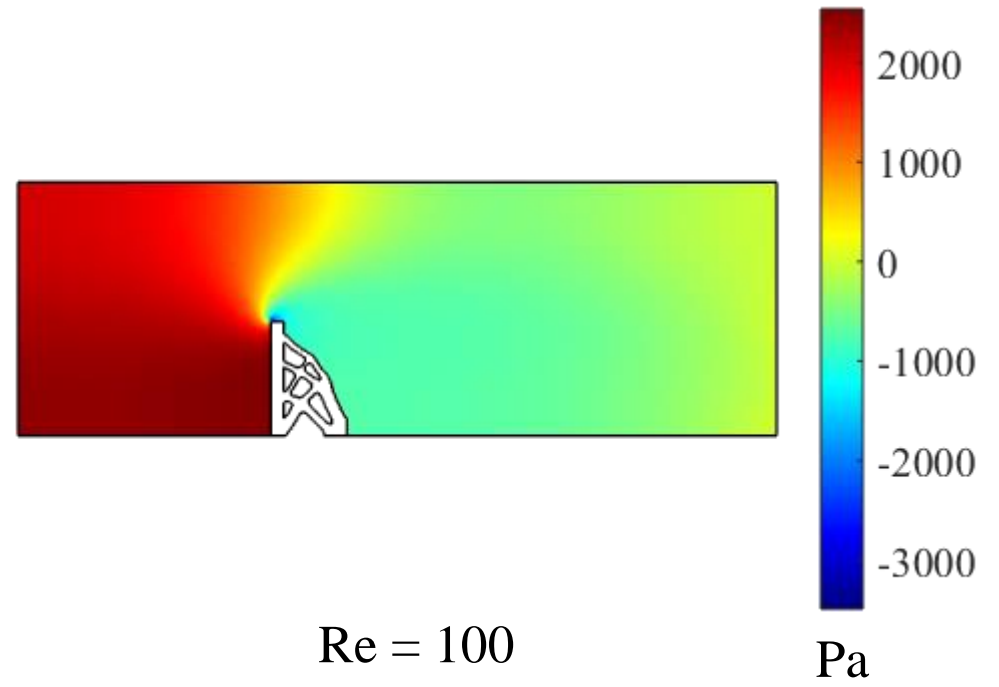
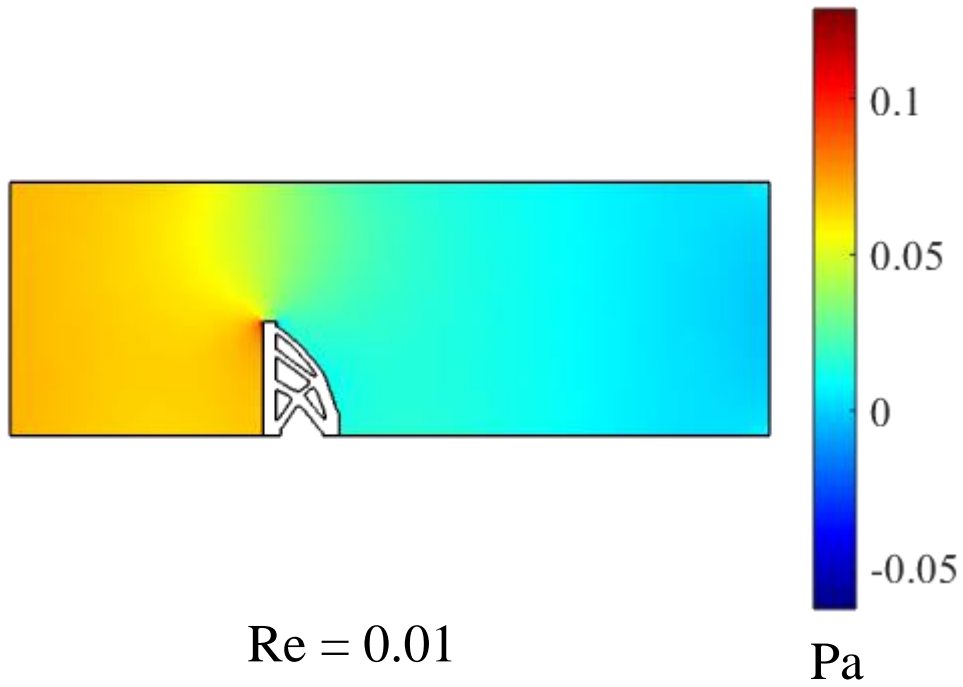
m/s



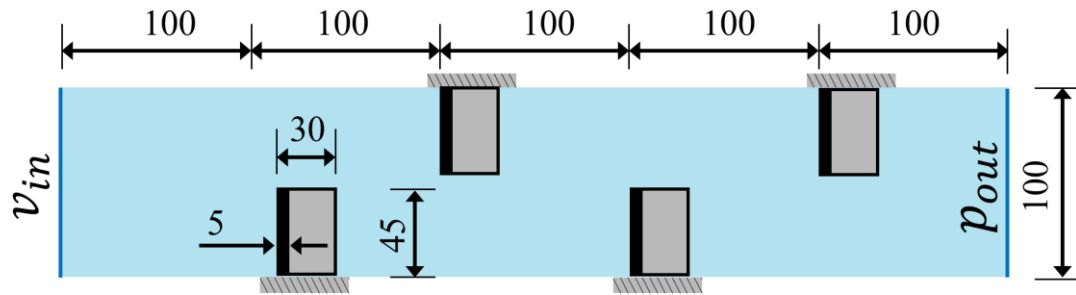
Examples: the wall



Examples: the wall



Examples: the seal



Minimum compliance

$$\bar{V} = 35\%$$

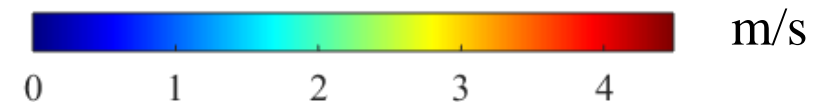
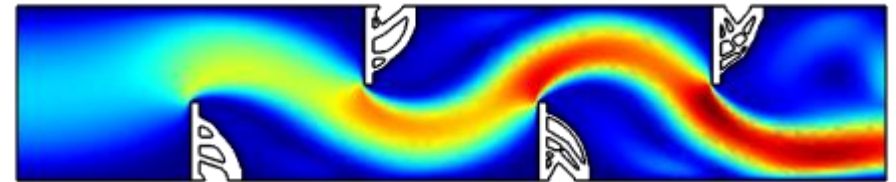
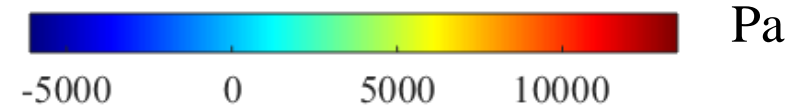
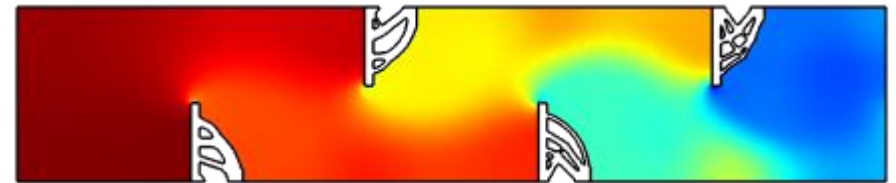
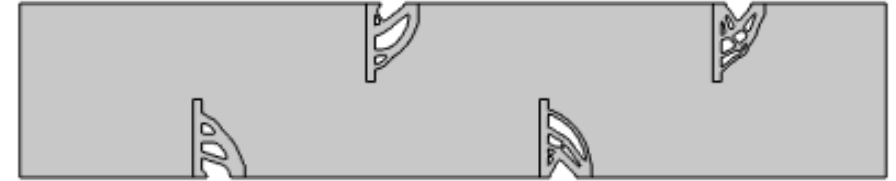
Solid: $E = 2 \cdot 10^5$ Pa, $\nu = 0.3$

Fluid: water

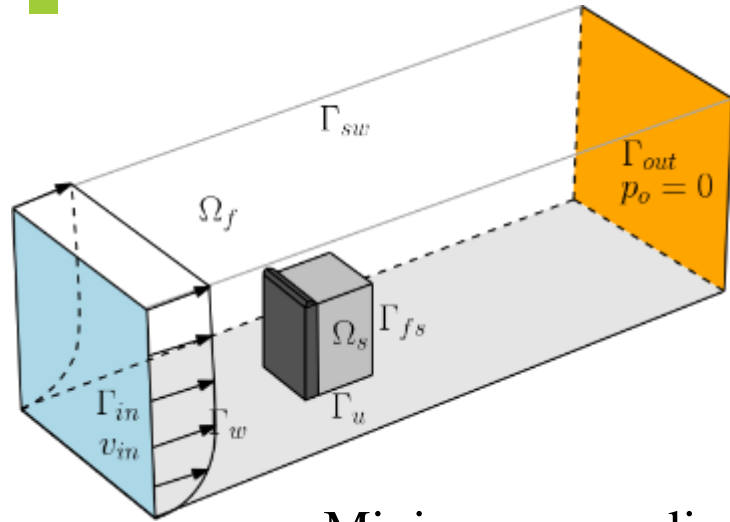
Re = 0.01

$\epsilon = 0.01$

$\beta = 0.05$



Examples: the 3D wall



Minimum compliance
 $\bar{V} = 35\%$

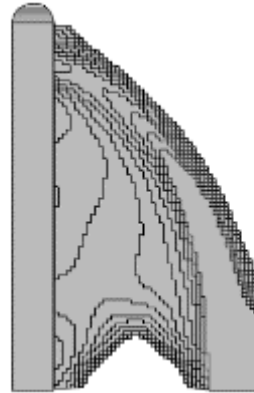
Solid: $E = 2 \cdot 10^5$ Pa, $\nu = 0.3$

Fluid: water

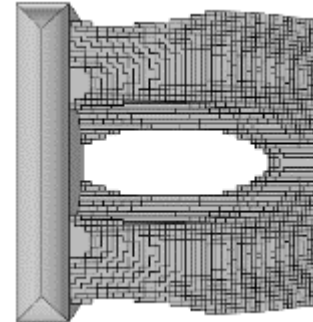
Re = 0.01

$\epsilon = 0.01$; $\beta = 0.05$

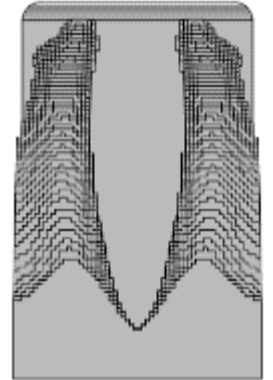
Side view



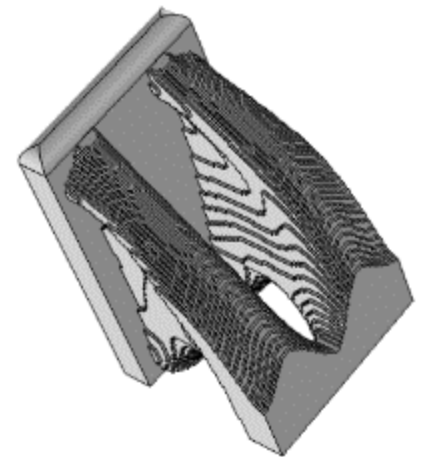
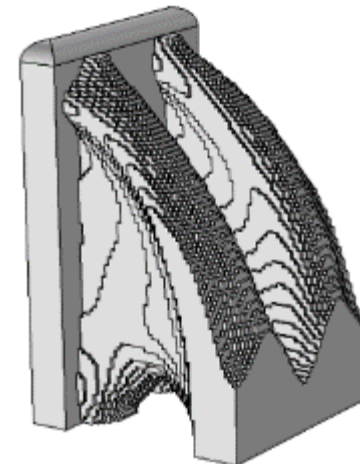
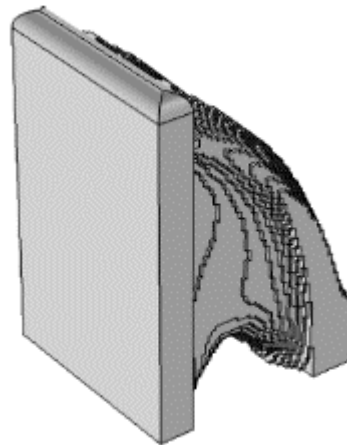
Top view



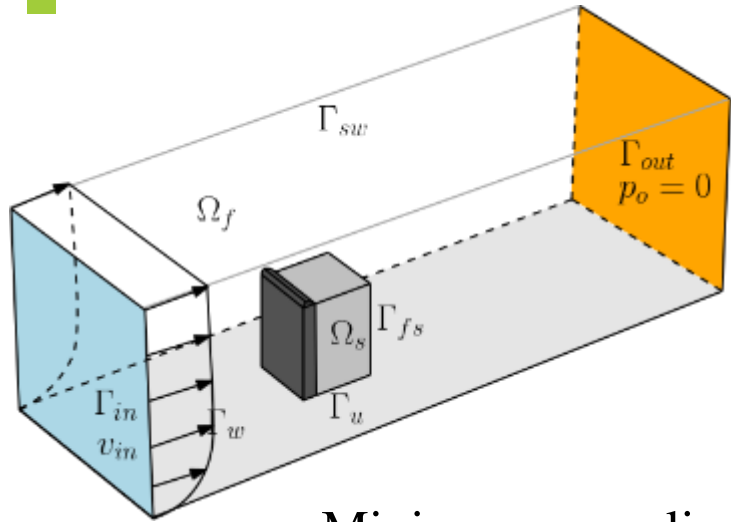
Back view



Rotated views



Examples: the 3D wall



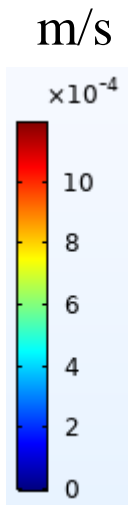
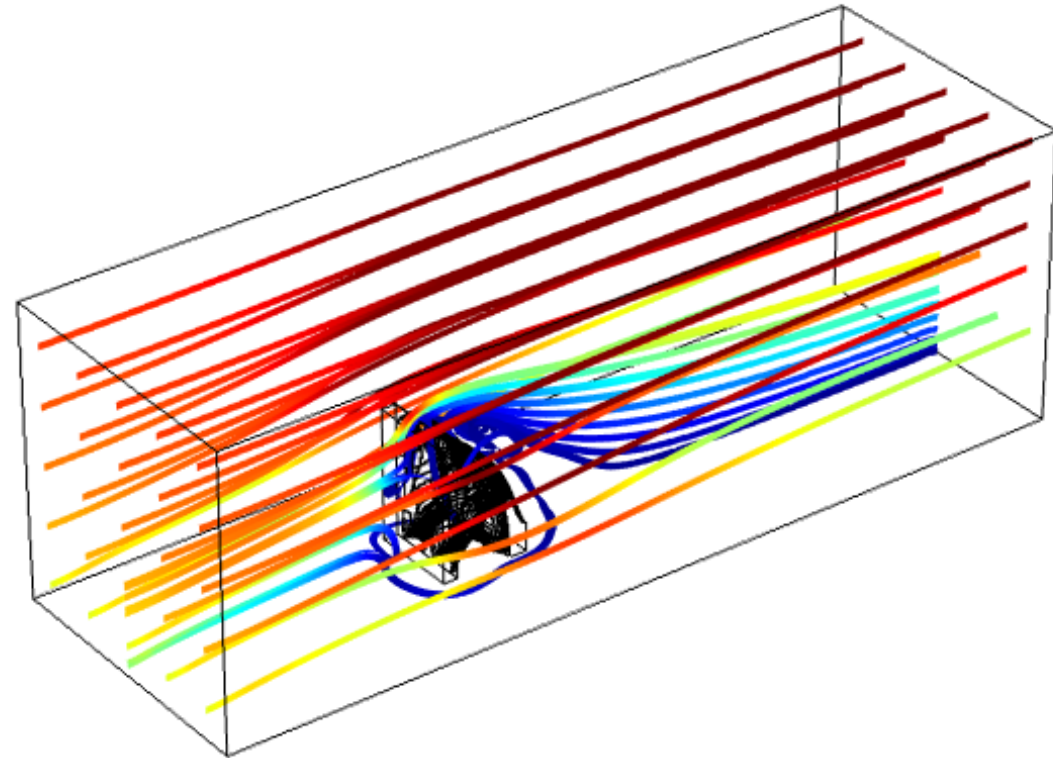
Minimum compliance
 $\bar{V} = 35\%$

Solid: $E = 2 \cdot 10^5$ Pa, $\nu = 0.3$

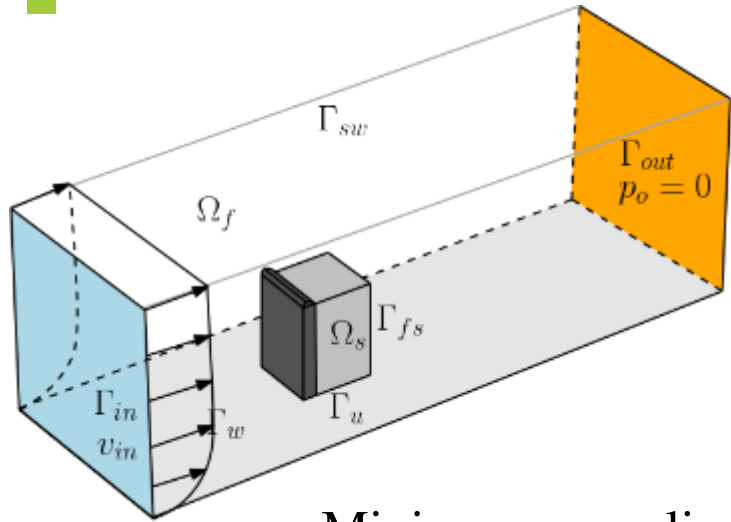
Fluid: water

Re = 0.01

$\epsilon = 0.01$; $\beta = 0.05$



Examples: the 3D wall



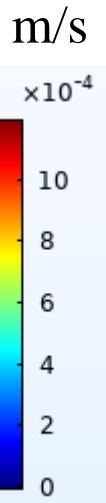
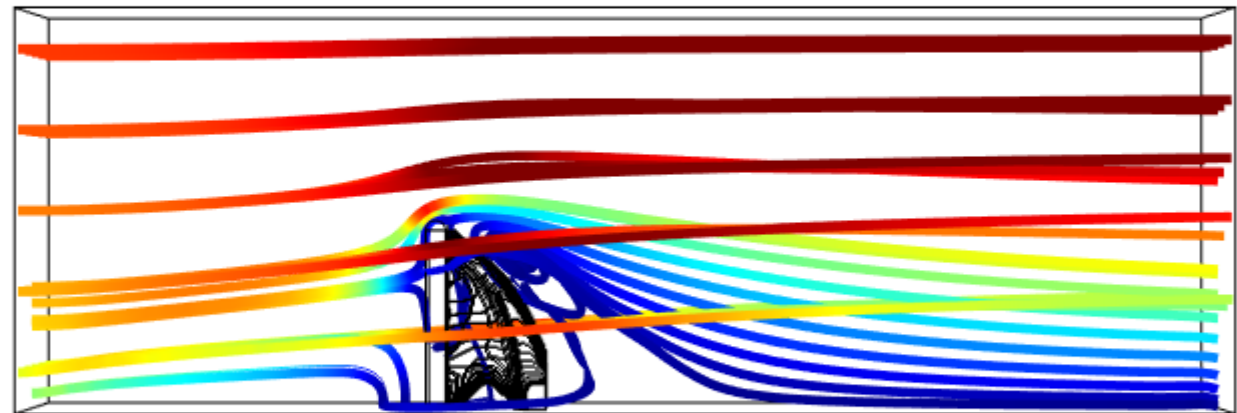
Minimum compliance
 $\bar{V} = 35\%$

Solid: $E = 2 \cdot 10^5$ Pa, $\nu = 0.3$

Fluid: water

Re = 0.01

$\epsilon = 0.01$; $\beta = 0.05$



Conclusions

- Compliance minimization of structures under fluid-structure interaction loads was successfully solved
- The TOBS approach is suitable for the problem
- A new methodology of decoupling analysis and simulation was proposed in the context of binary design variables
- Future work should increase the complexity of the FSI simulation

References

- [1] R Picelli, A Neofytou and H A Kim. Topology optimization for design-dependent hydrostatic pressure loading via the level-set method. *Structural and Multidisciplinary Optimization*, 60(4):1313-1326, 2019.
- [2] C Lundgaard, J Alexand, M Zhou, C Andreasen, and O Sigmund. Revisiting density-based topology optimization for fluid-structure-interaction problems. *Structural and Multidisciplinary Optimization*, 58:969-995, 2018.
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- [5] R Picelli, W M Vicente, and R Pavanello. Evolutionary topology optimization for structural compliance minimization considering design-dependent fsi loads. *Finite Elements in Analysis and Design*, 135:44-55, 2017.
- [6] R Picelli, R Sivapuram. Topology optimization of binary structures using Integer Linear Programming. *Finite Elements in Analysis and Design*, 139:49-61, 2020.
- [7] R Picelli, R Sivapuram and Y M Xie. A 101-line MATLAB code for topology optimization using binary variables and integer programming. *Structural and Multidisciplinary Optimization*, online, published 27 September 2020.
- [8] R Picelli, S Ranjbarzadeh, R Sivapuram, R S Gioria, and E C N Silva. Topology optimization of binary structures under design-dependent fluid-structure interaction loads. *Structural and Multidisciplinary Optimization*, 62:2101-2116, 2020.



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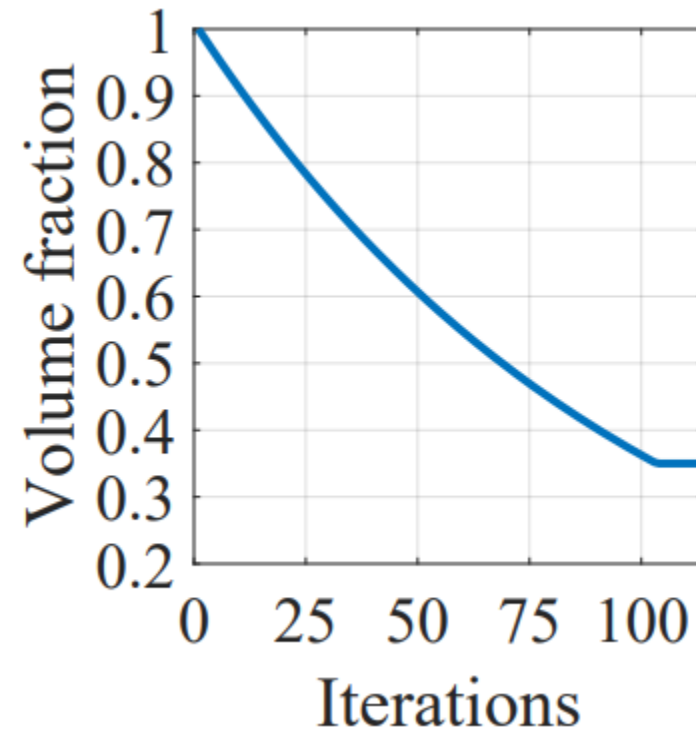
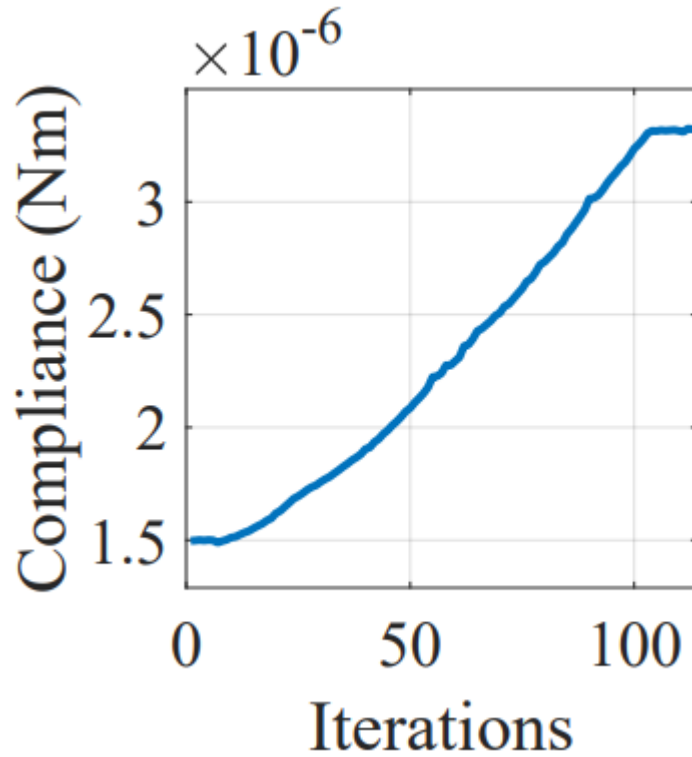
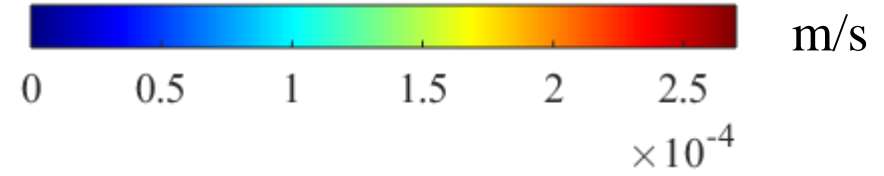
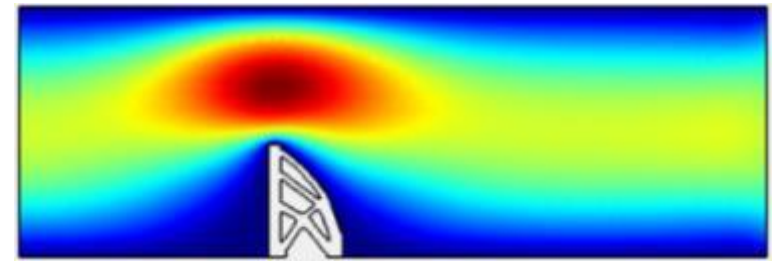
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Design method sheet

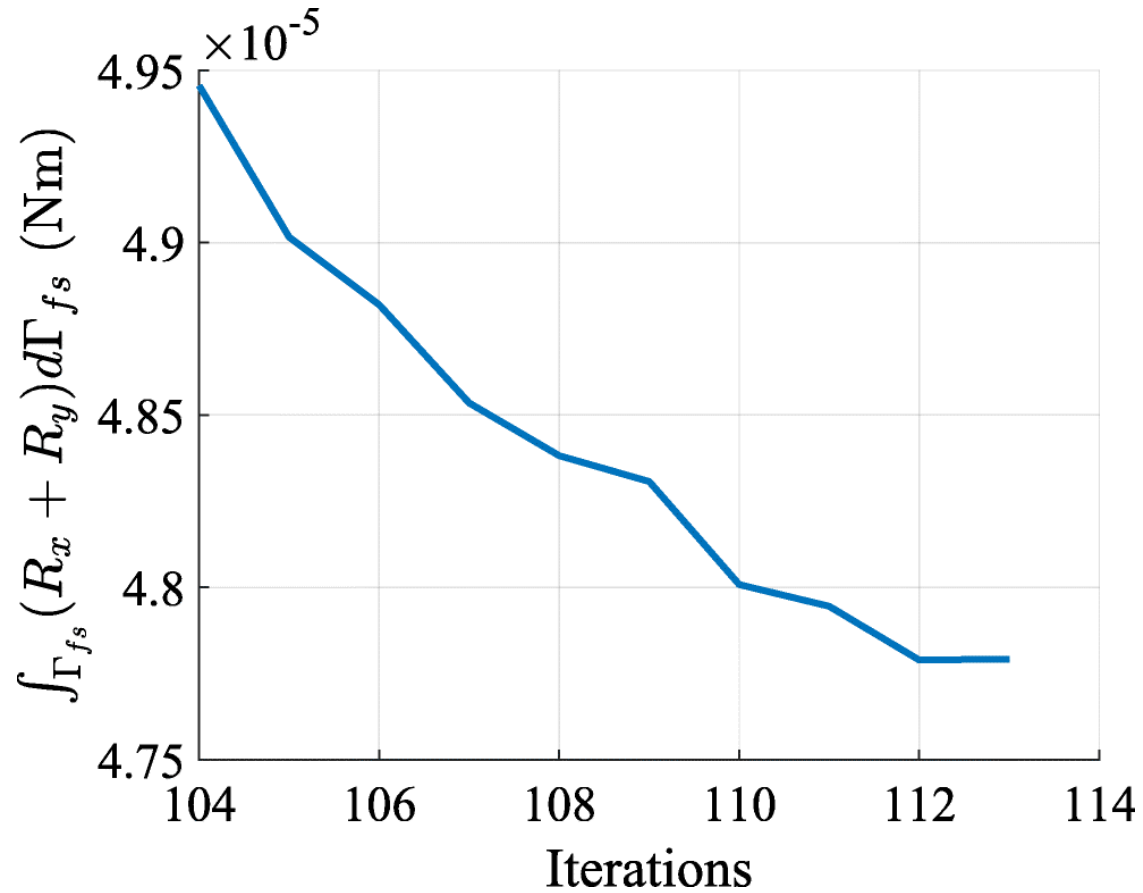
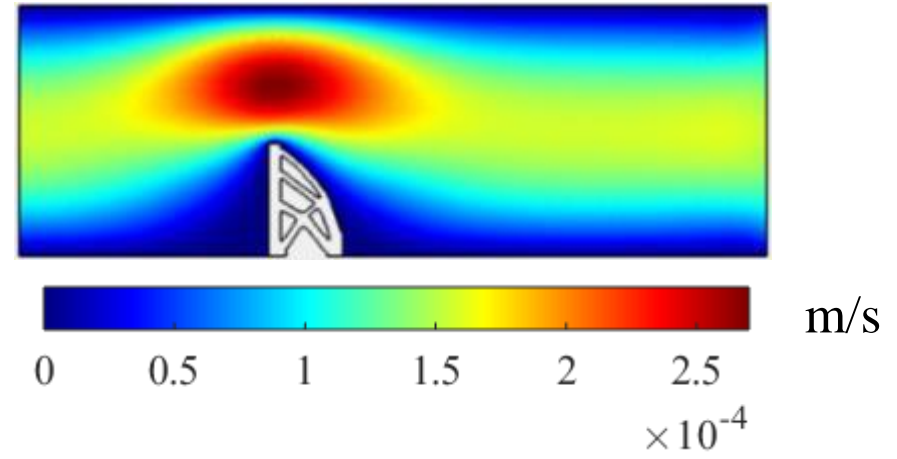
Design method specifications

- Topology optimization variables
 - density-based interpolation
 - binary {0,1}
 - boundary description (level set)
- Governing equations
 - monolithic (mixed model)
 - separate
- Mesh type
 - remeshing
 - global
 - local (XFEM)
 - fixed grid
- Sensitivity analysis
 - element-based
 - material interpolation
 - discrete
 - point-based
 - material interpolation
 - shape sensitivities

Examples: the wall

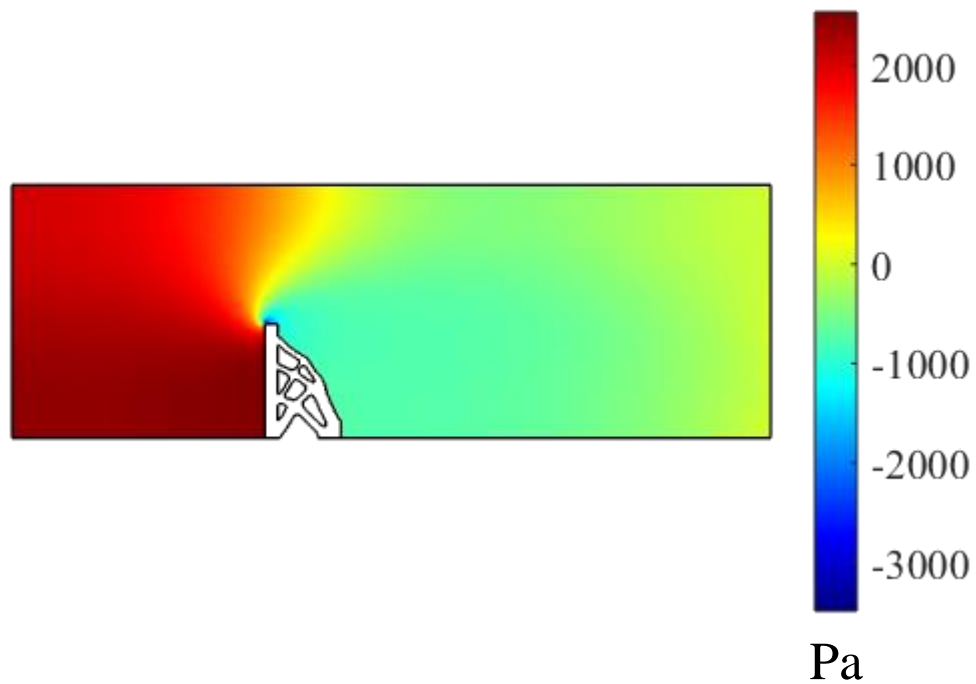


Examples: the wall

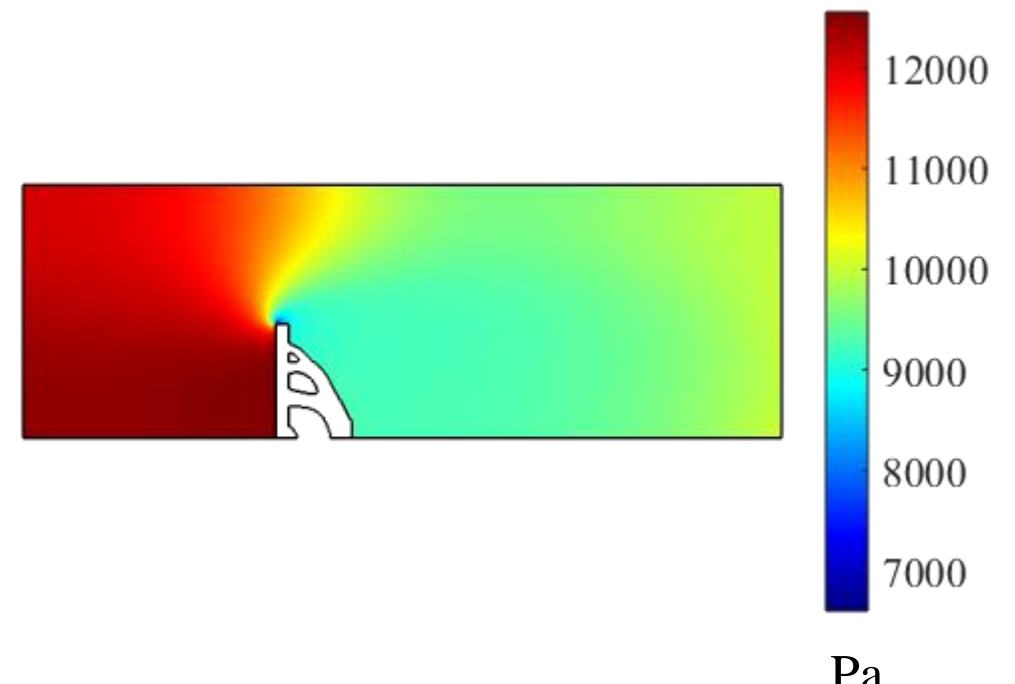


Examples: the wall, reference pressure

Re = 100

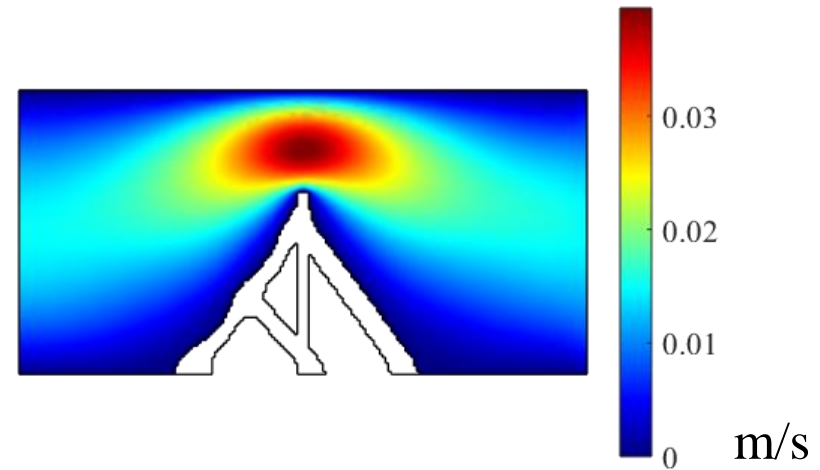
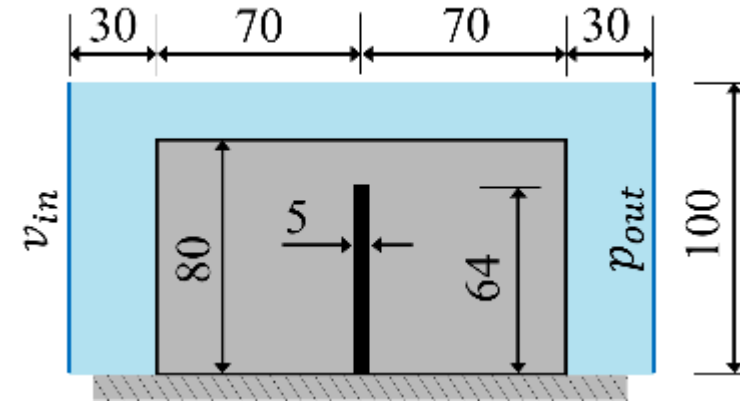
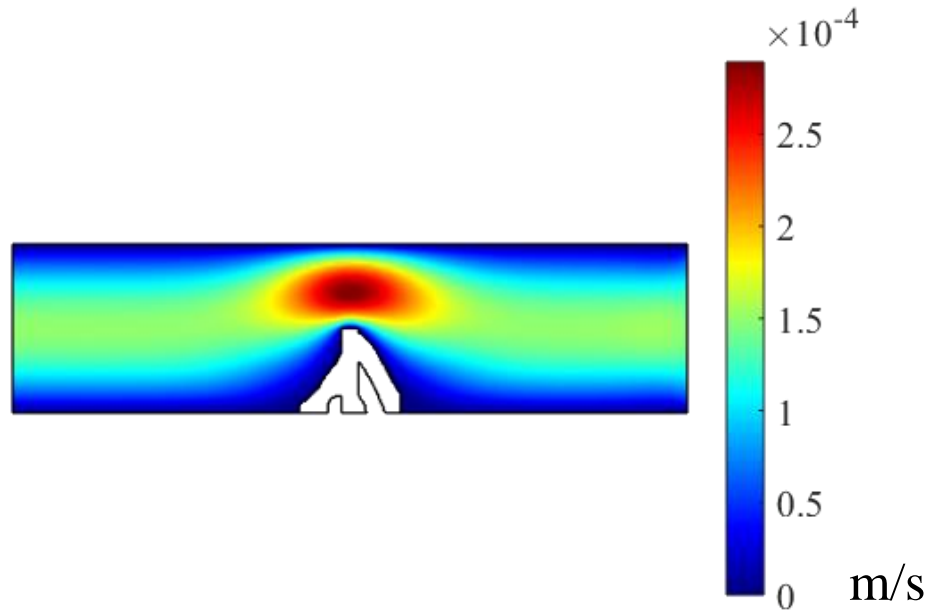
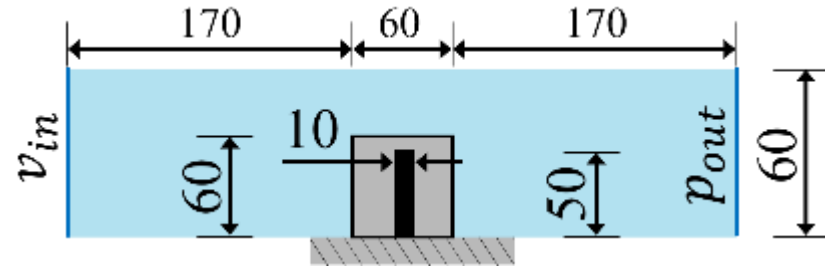


$p_0 = 0$



$p_0 = 1 \cdot 10^4$ Pa

Other examples



ILP – Computational time

Mesh size	Iterations	FEA (sec)	ILP (sec)
50 × 50	83	3.926	6.366
100 × 100	95	39.330	9.510
200 × 200	170	547.264	59.041
400 × 400	234	9429.989	129.589

R Sivapuram and R Picelli. Topology design of binary structures subjected to design-dependent thermal expansion and fluid pressure loads. *Structural and Multidisciplinary Optimization*, 61:1877–1895, 2020.