



Topology Optimization of Dynamic Acoustic-Mechanical Structures using the Ersatz Material Model

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Outline

- ❑ **Research Motivation**
- ❑ **Topology Optimization Algorithm**
- ❑ **Numerical Examples**
- ❑ **Concluding Remarks**

- ❑ In real applications, there are many acoustic-mechanical structures and devices which have designated functionalities, such as sound insulation, vibration isolation, etc.
- ❑ Topology optimization of structures considering acoustic-mechanical coupling has been widely investigated.

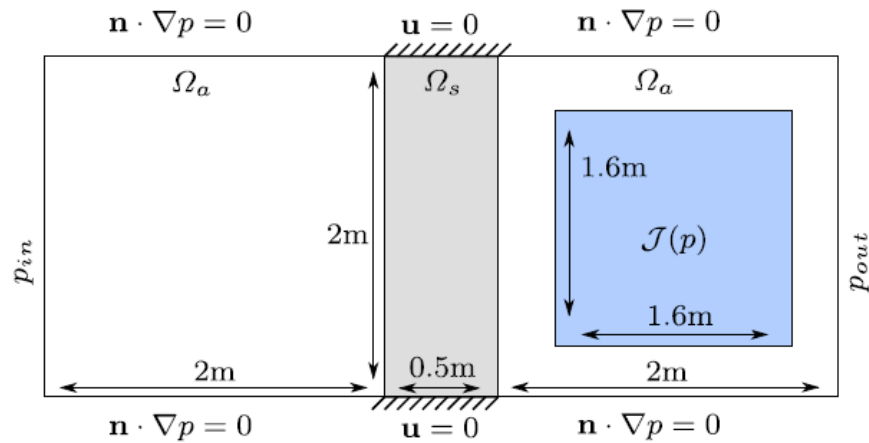
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B.D. Cetin, S.B. Dilgen, N. Aage, J.S. Jensen. Topology optimization of acoustic mechanical interaction problems: a comparative review. *Structural and Multidisciplinary Optimization*. 60(2) (2019) 779-801.

□ Benchmark problem

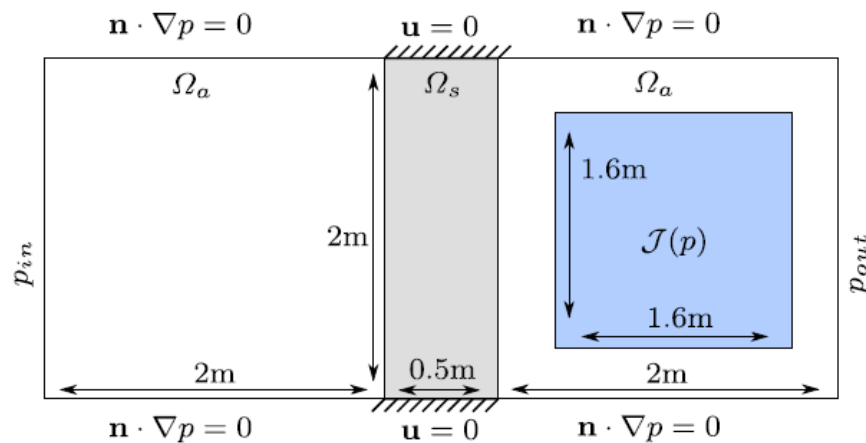


$$\min: J(p) = \int_{\Omega_{obj}} |p| d\Omega$$
$$V_f \leq V^*$$

- the mixed \mathbf{u}/p formulation
- the segregated formulation

Research Motivation

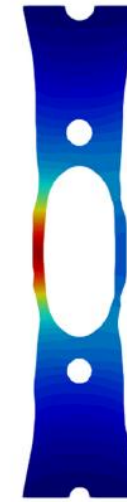
□ Benchmark problem



$$\min: J(p) = \int_{\Omega_{\text{obj}}} |p| \, d\Omega$$

$$V_f \leq V^*$$

Boundary-based
level-set method:



$$J = 68.7\text{N}$$

the mixed u/p
formulation

Element-based density
method (RAMP):



$$J = 48.9\text{N}$$

However, the thresholded density-based design using the segregated formulation gives a 28.6% reduction in objective value ($J = 34.9 \text{ N}$).

Built on the previous researches, this paper investigates element-based topology optimization of acoustic-mechanical structures using the **Ersatz material model**. The bulk modulus, shear modulus and density of each element are linearly interpolated as

$$\begin{cases} K(x_i) = K_s x_i + K_a (1 - x_i) \\ G(x_i) = G_s x_i \\ \rho(x_i) = \rho_s x_i + \rho_a (1 - x_i) \end{cases}$$

$x_i = 0$ means the element is composed of the acoustic medium (e.g. air) and $x_i = 1$ for the solid medium.

The potential advantages of using the linear Ersatz material model include

- ❑ Achieving the consistency of objective value in the mixed **u/p** formulation and the segregated formulation
- ❑ Overcoming artificial vibration modes during optimization process

Topology optimization problem

$$\text{Min.: } J(\mathbf{x}, \mathbf{U}(\mathbf{x}))$$

$$\text{S. t.: } V_f \leq V_f^*$$

$$\begin{cases} x_i = 1 & \text{when } x_i \in \Omega_{\text{solid}} \\ x_i = 0 & \text{when } x_i \in \Omega_{\text{acoustic}} \\ 0 < x_i < 1 & \text{when } x_i \text{ at the acoustic – solid boundary} \end{cases} \quad \rightarrow \text{0/1 constraints of design variables}$$

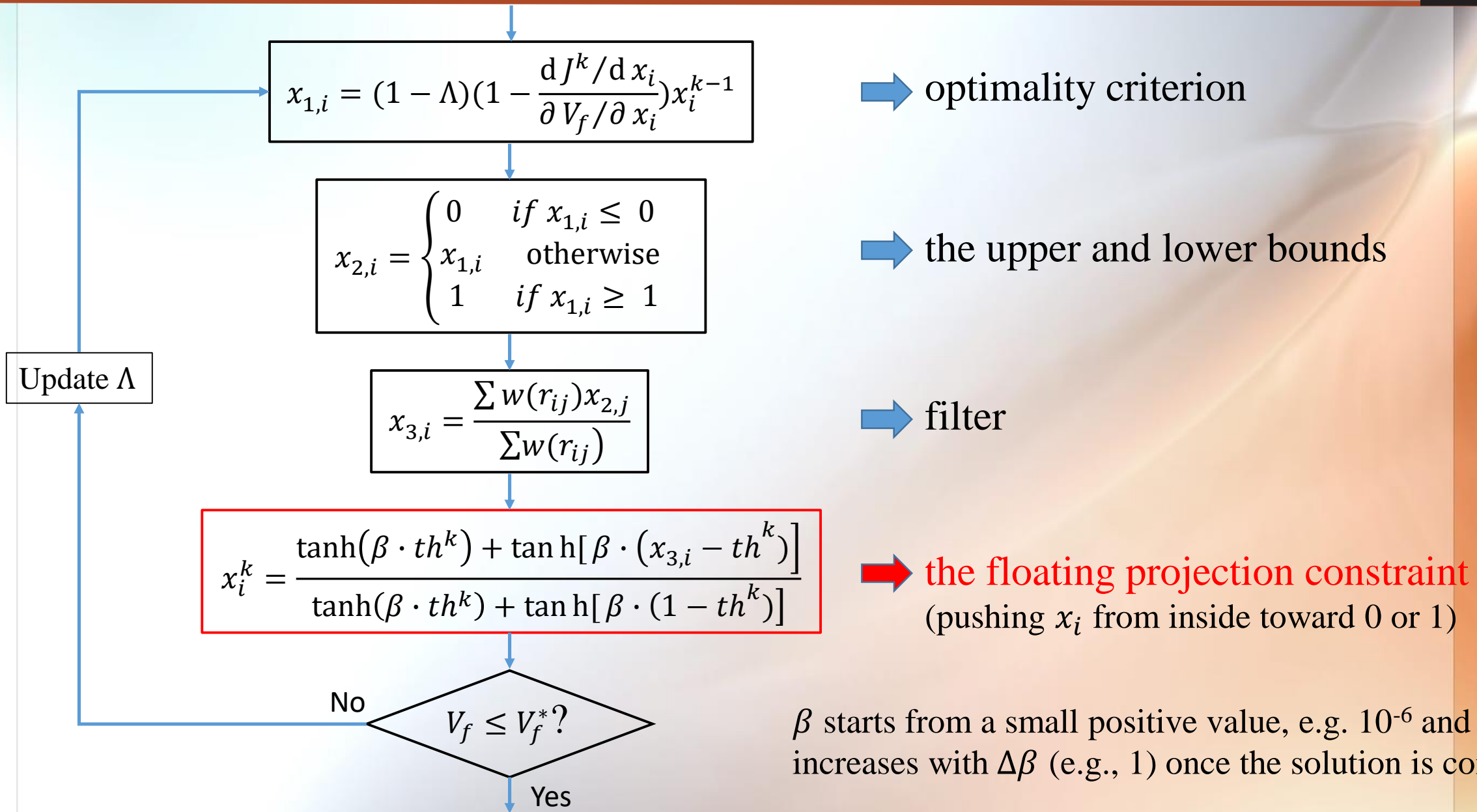
To solve the optimization problem using the relaxed design variables, $0 \leq x_i \leq 1$, the objective function is modified by introducing Lagrange multipliers for all constraints as

$$\text{Min.: } f = J(\mathbf{x}, \mathbf{U}(\mathbf{x})) + \Psi(V_f - V_f^*) + \sum \underbrace{\Psi_j(g_j - g_j^*)}_{\text{floating projection constraint}}$$

the upper and lower bounds of design variables

the floating projection constraint, which simulates the original 0/1 constraints together with the upper and lower bounds of design variables.

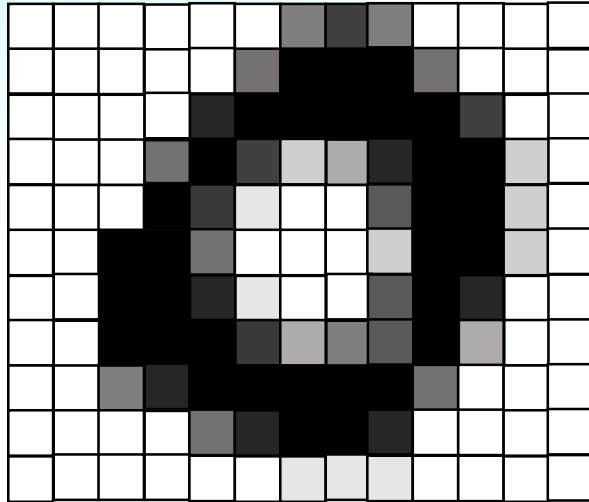
Numerical implementation



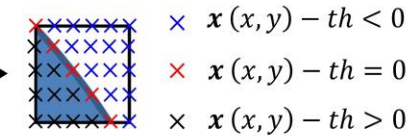
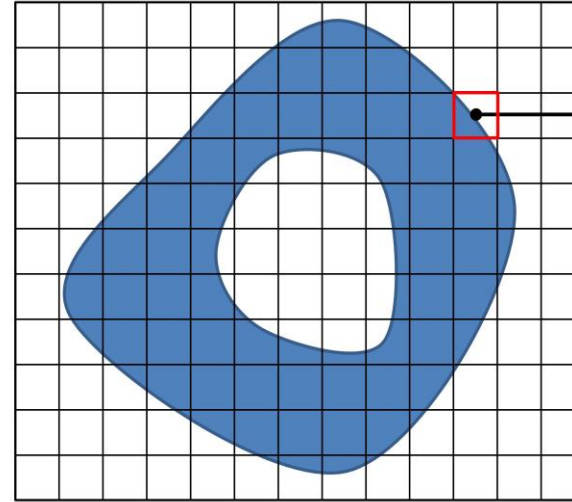
β starts from a small positive value, e.g. 10^{-6} and then increases with $\Delta\beta$ (e.g., 1) once the solution is convergent.

Representation of optimized topology for CAD-ready model

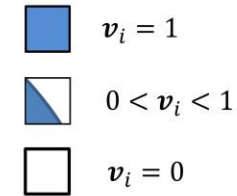
Convergent solution for a given β



Graphic processing





Volume fraction



$$\mathbf{x}^k = \{x_1^k, x_2^k, \dots, x_i^k, \dots, x_N^k\}^T$$

$$\mathbf{v}^k = \{v_1^k, v_2^k, \dots, v_i^k, \dots, v_N^k\}$$

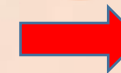
$\beta = \beta + \Delta\beta$  

$$\tau = \frac{1}{N} \sum_{i=1}^N (x_i^k - v_i^k)^2 \leq 0.001$$

and/or

$$\tau = \left| \frac{J(\mathbf{x}, \mathbf{U}(\mathbf{x})) - J(\mathbf{v}, \mathbf{U}(\mathbf{v}))}{J(\mathbf{x}, \mathbf{U}(\mathbf{x}))} \right| \leq 0.01$$

FEA on \mathbf{v}^k



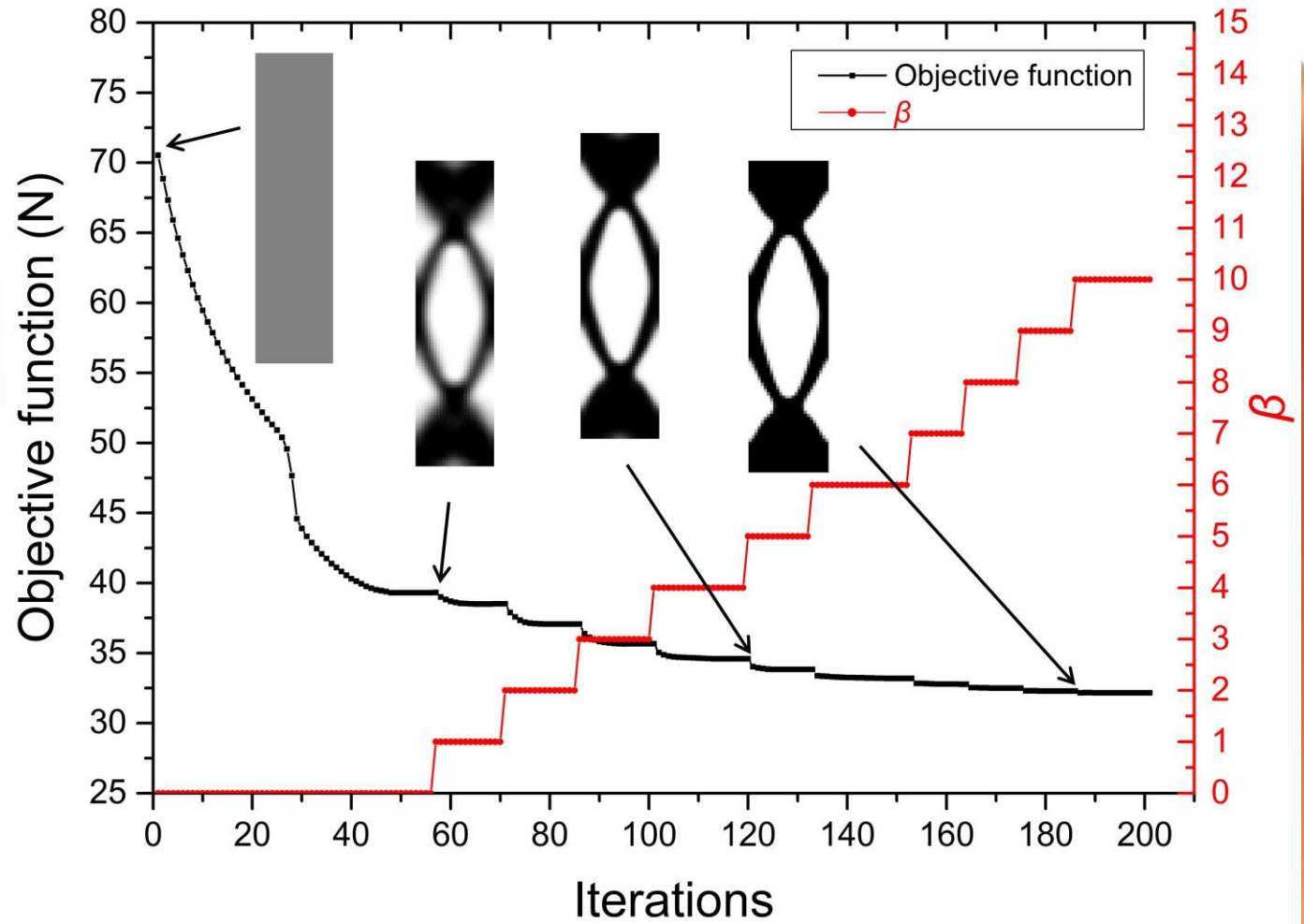
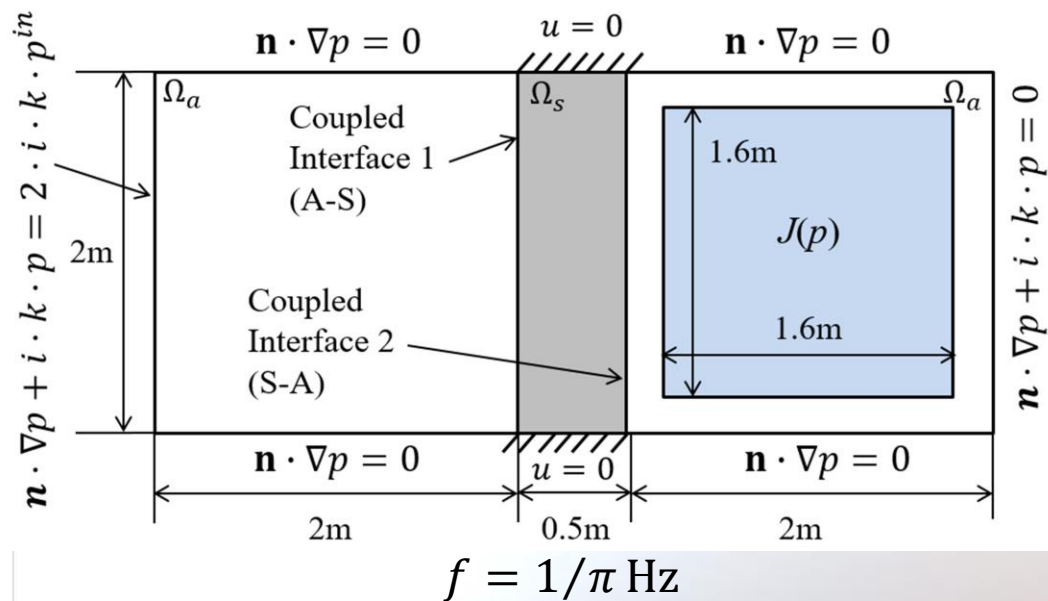
Stop optimization

Sound insulation

□ Revisiting the benchmark problem

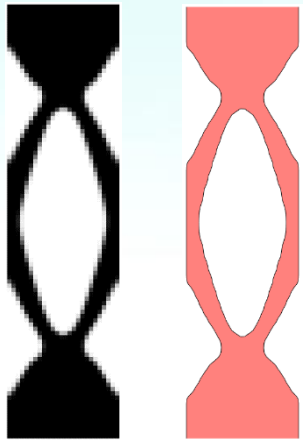
$$\min: J(p) = \int_{\Omega_{\text{obj}}} |p| \, d\Omega$$

$$\text{s. t. : } V_f \leq V^*$$



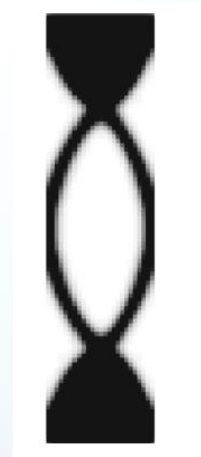
Sound insulation

□ Revisiting the benchmark problem



$$J = 32.16 \text{ N}$$
$$(\mathbf{u}/p)$$

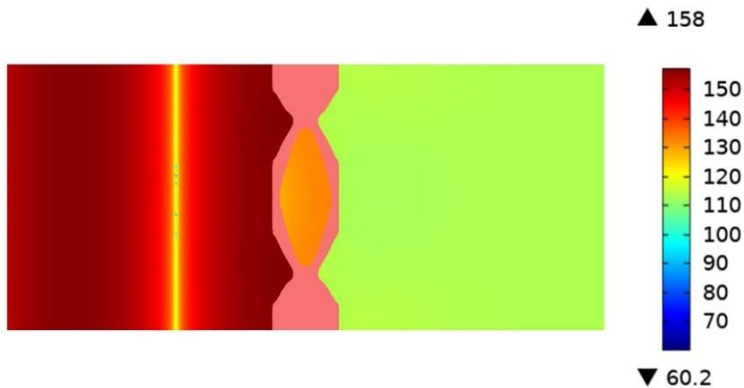
Current design



$$J = 48.9 \text{ N}$$
$$(\mathbf{u}/p)$$

$$J = 34.9 \text{ N}$$
$$(\text{segregated})$$

Density-based design*



$$J = 32.43 \text{ N}$$
$$(\text{segregated})$$

Only 0.84% relative difference

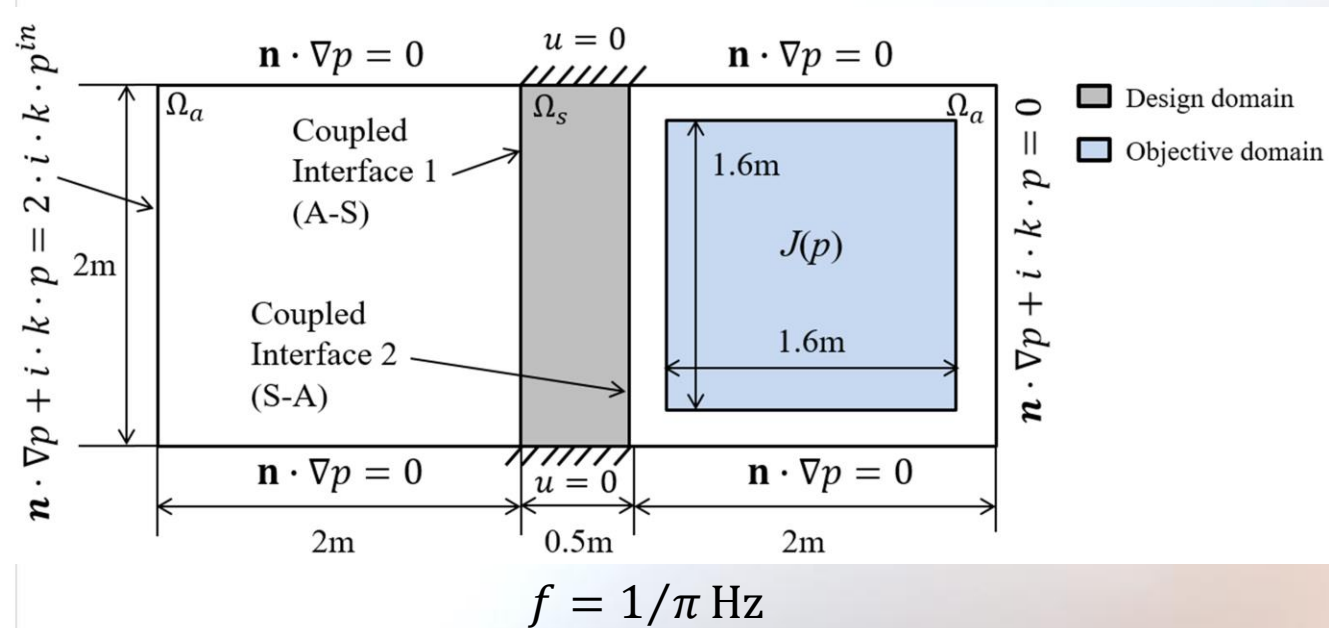
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Sound insulation

□ Lightweight design

$$\text{min.} : V_f$$

$$\text{s. t.} : J(\mathbf{x}, \mathbf{U}(\mathbf{x})) \leq J^* = 40\text{N}$$



Sound insulation

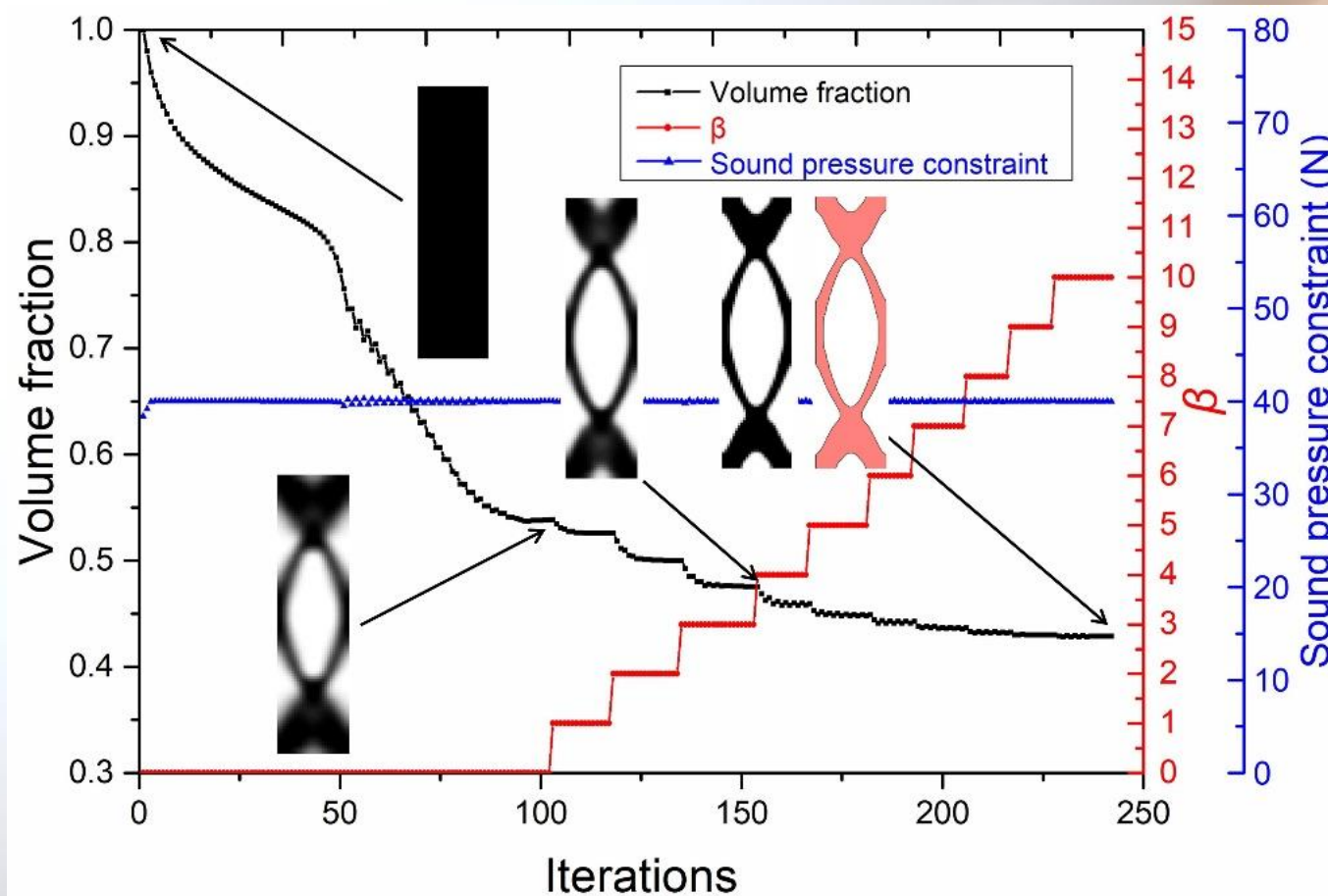
□ Lightweight design

$$\text{min. : } V_f$$

$$\text{s. t. : } J(\mathbf{x}, \mathbf{U}(\mathbf{x})) \leq J^* = 40\text{N}$$

$$J = 39.71\text{N}$$

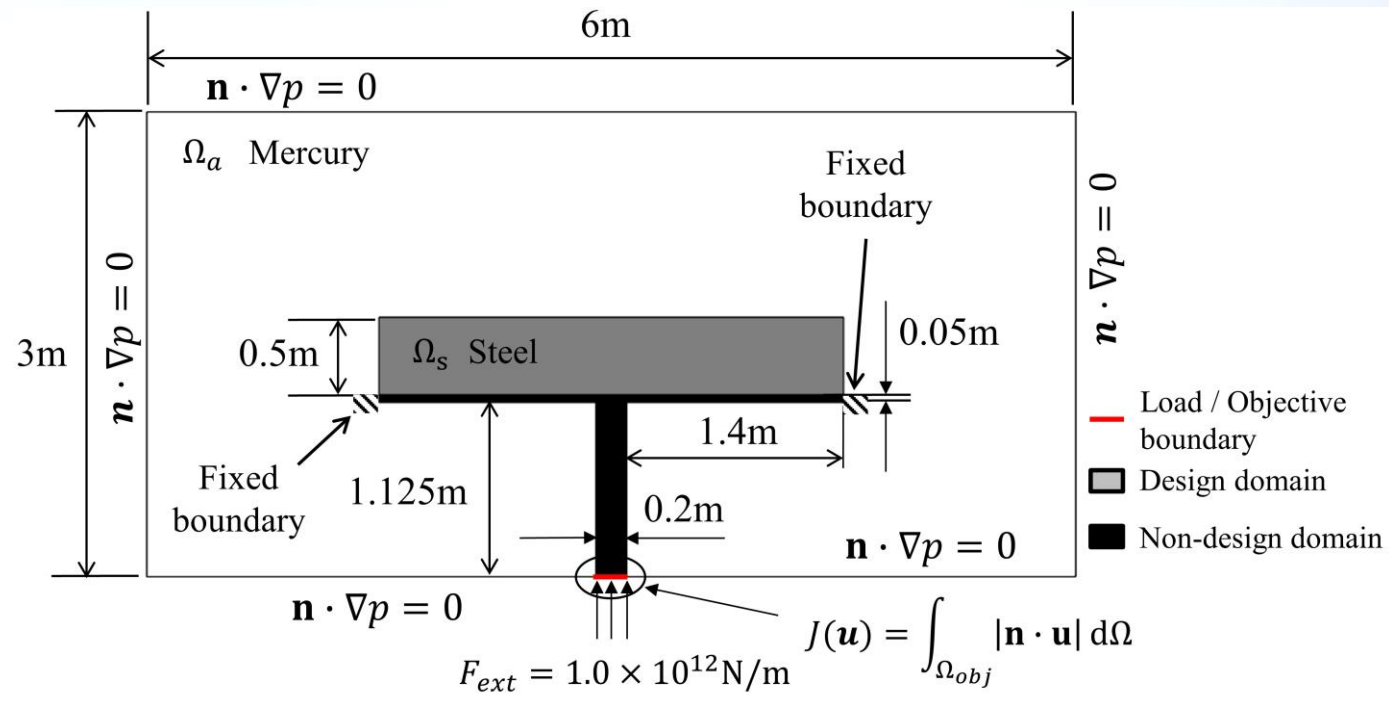
(segregated)



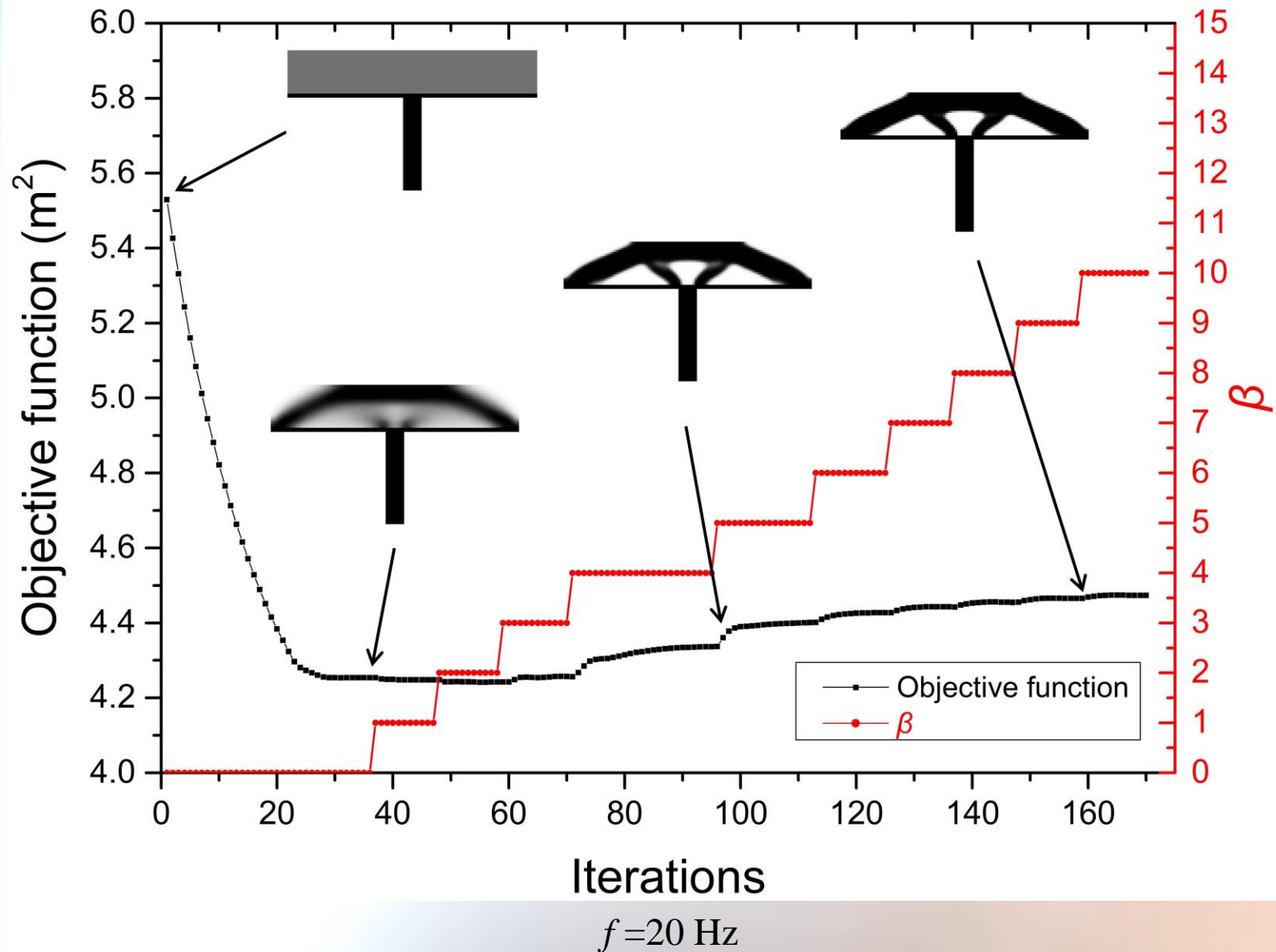
$$V_{f\text{min}} = 0.428$$

Vibration reduction

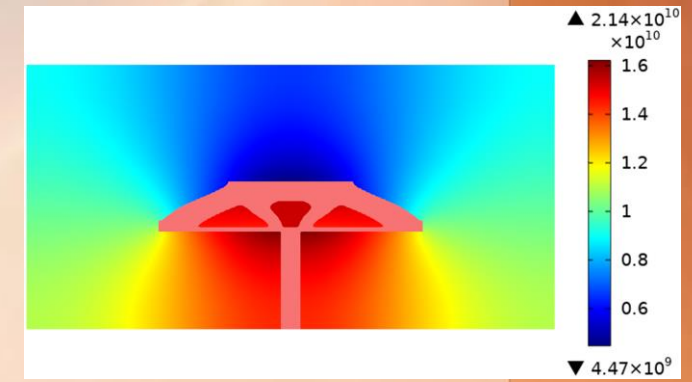
$$\min: J(\mathbf{u}) = \int_{\Omega_{obj}} |\mathbf{n} \cdot \mathbf{u}| \, d\Omega \quad (\text{vibration amplitude})$$



Vibration reduction



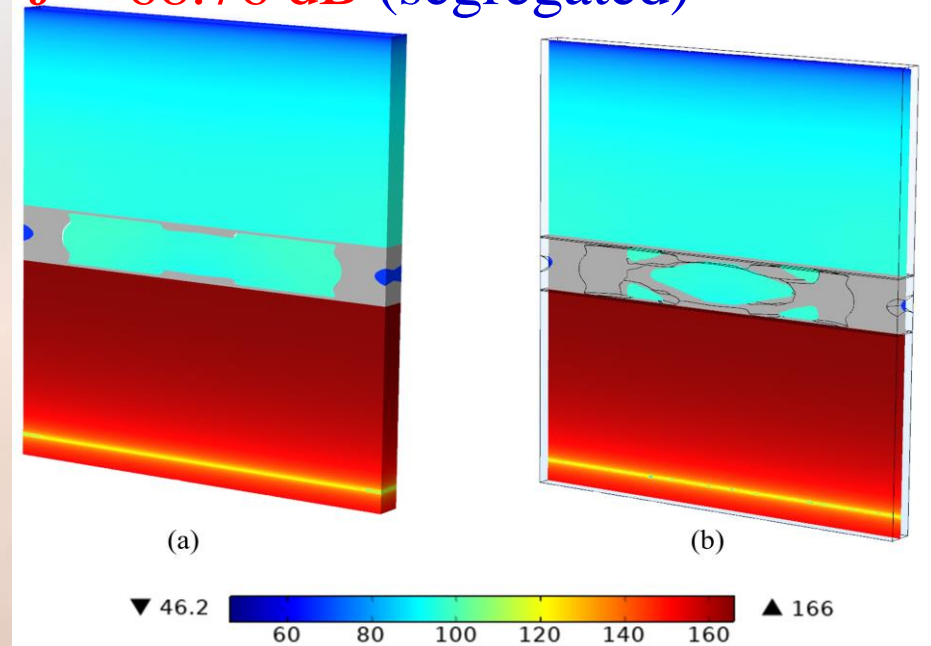
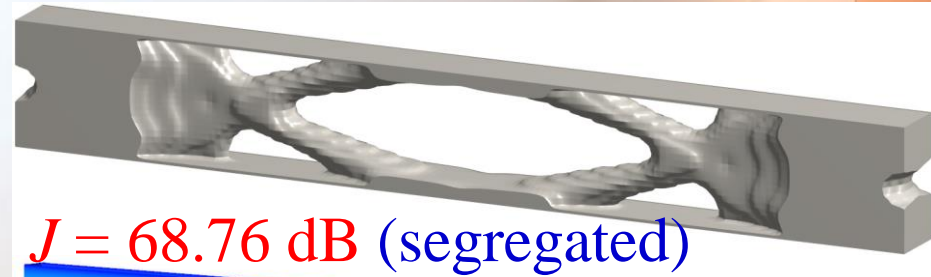
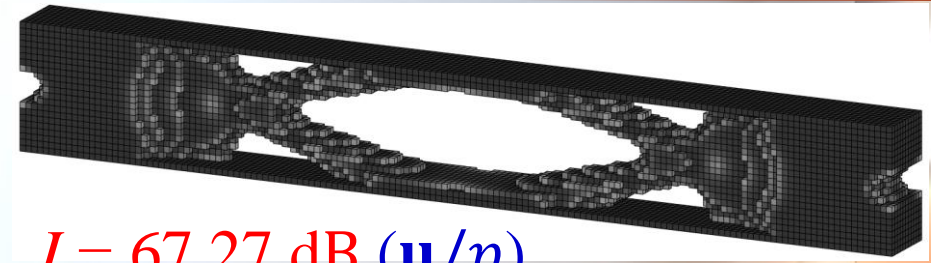
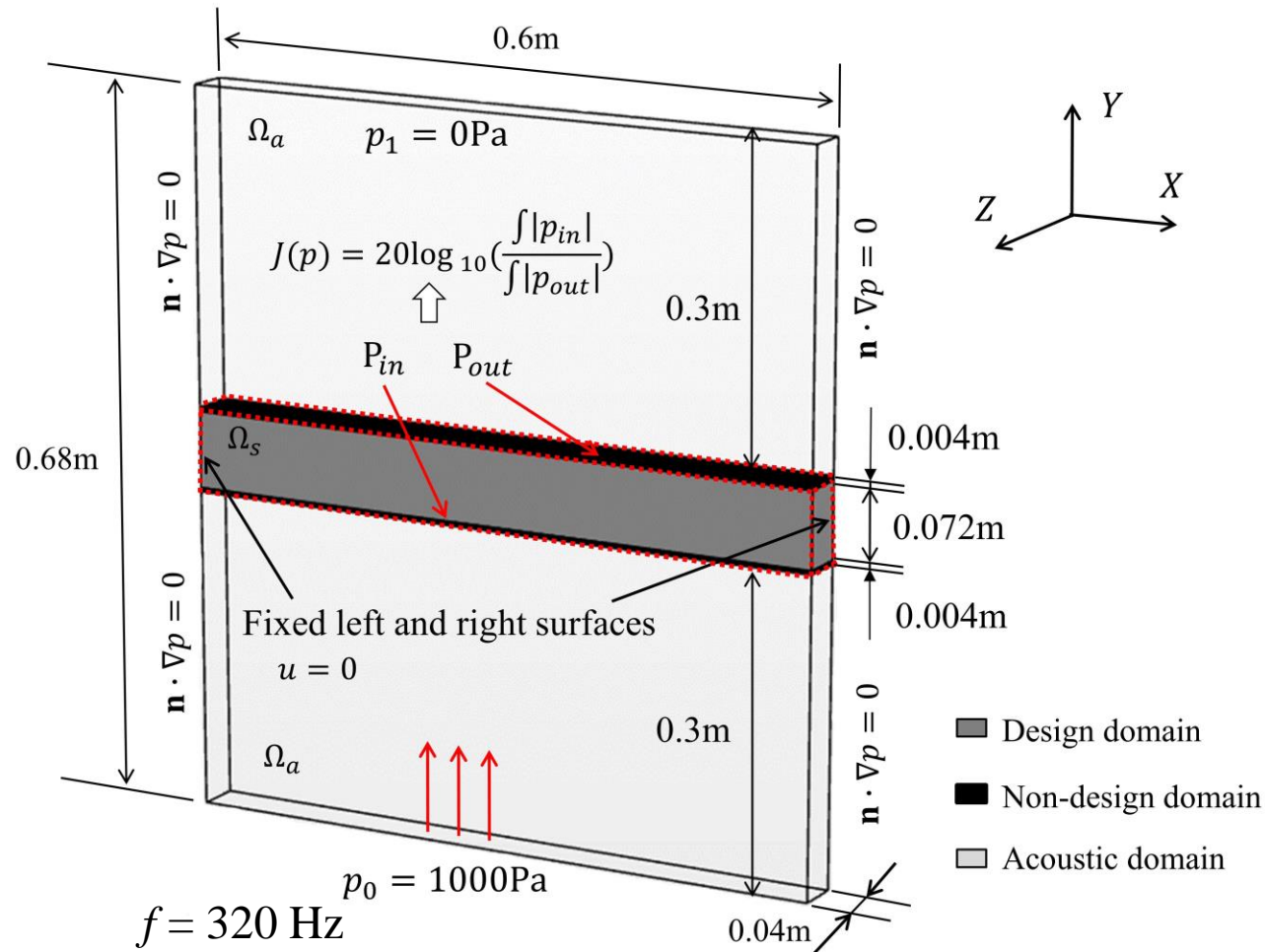
$J = 4.47 \text{ m}^2$
(u/p)



$J = 4.51 \text{ m}^2$
(segregated)

Maximizing sound transmission loss

$$\min: -J(p) = -20\log_{10}\left(\frac{|P_{in}|}{|P_{out}|}\right)$$



Concluding remarks

- ❑ This paper proposes a new topology algorithm for designing acoustic-mechanical structures using the linear ersatz material model.

- ❑ The advantages of the proposed algorithm include
 - the consistency between the the mixed \mathbf{u}/p formulation and the segregate formulation
 - no artificial vibration modes during optimization
 - integration of the post-processing of element-based optimized design in optimization

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Abstract

Topology optimization of dynamic acoustic–mechanical structures is challenging due to the interaction between the acoustic and structural domains and artificial localized vibration modes of structures. This paper presents a floating projection topology optimization (FPTO) method based on the mixed displacement/pressure (\mathbf{u}/p) finite element formulation and the ersatz material model. The former is able to release the need for tracking the interface boundaries explicitly between the structural and acoustic

Thank you

